

# Operator's Manual

Firmware V6.20 and higher



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## Table of Contents

<b>1. Safety Instructions</b>	<b>5</b>
1.1. Warning Notices	6
1.2. General Safety Regulations	8
<b>2. Product Description</b>	<b>9</b>
2.1. Description of the System	9
2.2. Instrument Specification	12
2.3. Instrument Overview	14
2.4. Single Components	15
2.4.1 AMI Solicon4 Transmitter	15
2.4.2 Flow Cell M-Flow PG and M-Flow G1	16
2.4.3 Swansensor Shurecon P	17
2.4.4 Swansensor Shurecon S	18
2.4.5 Swansensor DeltaT	19
<b>3. Installation</b>	<b>20</b>
3.1. Installation Checklist Monitors	20
3.2. Mounting of Instrument Panel	21
3.3. Connecting Sample Inlet and Outlet	21
3.4. Install Swansensor deltaT (Option)	22
3.4.1 Mount the deltaT Sensor and Connect the Sample Inlet	23
3.4.2 Connect the Sensor Cable to the Transmitter	24
3.4.3 Change Firmware Settings	25
3.4.4 Adjust the deltaT sensor	26
3.5. Electrical Connections	27
3.5.1 Connection Diagram	29
3.5.2 Power Supply	30
3.6. Relay Contacts	31
3.6.1 Input	31
3.6.2 Alarm Relay	31
3.6.3 Relay Contacts 1 and 2	32
3.7. Signal Outputs	34
3.7.1 Signal Output 1 and 2 (current outputs)	34
3.8. Interface Options	34
3.8.1 Signal Output 3	35
3.8.2 Profibus, Modbus Interface	35
3.8.3 HART Interface	36
3.8.4 USB Interface	36

<b>4.</b>	<b>Instrument Setup</b>	<b>37</b>
4.1.	Establish Sample Flow	37
4.2.	Programming	37
<b>5.</b>	<b>Operation</b>	<b>38</b>
5.1.	Keys	38
5.2.	Display	39
5.3.	Software Structure	40
5.4.	Changing Parameters and values	41
<b>6.</b>	<b>Maintenance</b>	<b>42</b>
6.1.	Maintenance Schedule	42
6.2.	Stop of Operation for Maintenance	42
6.3.	Maintenance of the Sensor	43
6.3.1	Remove the Sensor from the Flow Cell	43
6.3.2	Install the Sensor into the Flow Cell	43
6.4.	Calibration	44
6.5.	Longer Stop of Operation	45
<b>7.</b>	<b>Troubleshooting</b>	<b>46</b>
7.1.	Error List	46
7.2.	Replacing Fuses	49
<b>8.</b>	<b>Program Overview</b>	<b>50</b>
8.1.	Messages (Main Menu 1)	50
8.2.	Diagnostics (Main Menu 2)	51
8.3.	Maintenance (Main Menu 3)	52
8.4.	Operation (Main Menu 4)	52
8.5.	Installation (Main Menu 5)	53
<b>9.</b>	<b>Program List and Explanations</b>	<b>55</b>
1 Messages		55
2 Diagnostics		55
3 Maintenance		57
4 Operation		58
5 Installation		59
<b>10.</b>	<b>Default Values</b>	<b>74</b>
<b>11.</b>	<b>Index</b>	<b>77</b>
<b>12.</b>	<b>Notes</b>	<b>79</b>

# AMI Solicon4–Operator’s Manual

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This document describes the main steps for instrument setup, operation and maintenance.

## 1. Safety Instructions

<b>General</b>	<p>The instructions included in this section explain the potential risks associated with instrument operation and provide important safety practices designed to minimize these risks.</p> <p>If you carefully follow the information contained in this section, you can protect yourself from hazards and create a safer work environment.</p> <p>More safety instructions are given throughout this manual, at the respective locations where observation is most important. Strictly follow all safety instructions in this publication.</p>
<b>Target audience</b>	<p>Operator: Qualified person who uses the equipment for its intended purpose.</p> <p>Instrument operation requires thorough knowledge of applications, instrument functions and software program as well as all applicable safety rules and regulations.</p>
<b>OM Location</b>	<p>Keep the AMI Operator’s Manual in proximity of the instrument.</p>
<b>Qualification, Training</b>	<p>To be qualified for instrument installation and operation, you must:</p> <ul style="list-style-type: none"><li>♦ read and understand the instructions in this manual as well as the Material Safety Data Sheets.</li><li>♦ know the relevant safety rules and regulations.</li></ul>

## 1.1. Warning Notices

The symbols used for safety-related notices have the following meaning:



### **DANGER**

Your life or physical wellbeing are in serious danger if such warnings are ignored.

- ♦ Follow the prevention instructions carefully.



### **WARNING**

Severe injuries or damage to the equipment can occur if such warnings are ignored.

- ♦ Follow the prevention instructions carefully.



### **CAUTION**

Damage to the equipment, minor injury, malfunctions or incorrect process values can be the consequence if such warnings are ignored.

- ♦ Follow the prevention instructions carefully.

### **Mandatory Signs**

The mandatory signs in this manual have the following meaning:



Safety goggles



Safety gloves

**Warning Signs**    The warning signs in this manual have the following meaning:



Electrical shock hazard



Corrosive



Harmful to health



Flammable



Warning general



Attention general



## 1.2. General Safety Regulations

### Legal Requirements

The user is responsible for proper system operation. All precautions must be followed to ensure safe operation of the instrument.

### Spare Parts and Disposables

Use only official SWAN spare parts and disposables. If other parts are used during the normal warranty period, the manufacturer's warranty is voided.

### Modifications

Modifications and instrument upgrades shall only be carried out by an authorized Service Technician. SWAN will not accept responsibility for any claim resulting from unauthorized modification or alteration.

### WARNING

#### Electrical Shock Hazard



If proper operation is no longer possible, the instrument must be disconnected from all power lines, and measures must be taken to prevent inadvertent operation.

- ♦ To prevent from electrical shock, always make sure that the ground wire is connected.
- ♦ Service shall be performed by authorized personnel only.
- ♦ Whenever electronic service is required, disconnect instrument power and power of devices connected to.
  - relay 1,
  - relay 2,
  - alarm relay

### WARNING



For safe instrument installation and operation you must read and understand the instructions in this manual.

### WARNING



Only SWAN trained and authorized personnel shall perform the tasks described in this document.



## 2. Product Description

### 2.1. Description of the System

This instrument is applicable for the measurement of the specific conductivity in surface water, potable water and cooling water. The complete system consists of the transmitter AMI Solicon4, the conductivity sensor Swansensor Shurecon P and the flow cell M-Flow PG.

Transmitter, flow cell and sensors are also available as single components.

#### **Application Range**

Conductivity is a parameter for the total quantity of ions present in the solution. It can be used for the monitoring of:

- ♦ the condition of waters
- ♦ water purification
- ♦ water hardness
- ♦ completeness of ion analysis

#### **Signal Outputs**

Two signal outputs programmable for measured values (freely scalable, linear, bilinear, log) or as continuous control output (control parameters programmable).

Current loop: 0/4–20 mA

Maximal burden: 510 Ohm

Third signal output available as an option. The third signal output can be operated as a current source or as a current sink (selectable via switch).

#### **Relays**

Two potential-free contacts programmable as limit switches for measuring values, controllers or timer for system cleaning with automatic hold function. Both contacts can be used as normally open or normally closed.

Maximum load: 1 A/250 VAC

#### **Alarm Relay**

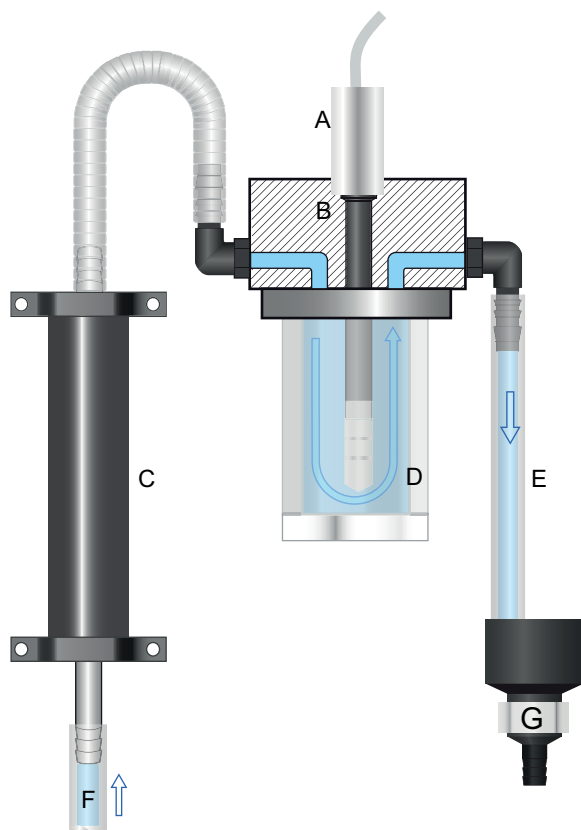
One potential free contact.

Alternatively:

- ♦ Open during normal operation, closed on error or loss of power.
- ♦ Closed during normal operation, open on error or loss of power.

Summary alarm indication for programmable alarm values and instrument faults.

<b>Input</b>	For potential-free contact to freeze the signal outputs or to interrupt control in automated installations ( <i>hold</i> function or <i>remote-off</i> ).
<b>Communication interface (optional)</b>	<ul style="list-style-type: none"> <li>♦ USB interface to store logger data.</li> <li>♦ Third signal output (can be used in parallel to the USB interface)</li> <li>♦ RS485 with Fieldbus protocol Modbus or Profibus DP</li> <li>♦ HART interface</li> </ul>
<b>Safety Features</b>	<p>No data loss after power failure. All data is saved in non-volatile memory.</p> <p>Over voltage protection of in- and outputs.</p> <p>Galvanic separation of measuring inputs and signal outputs.</p>
<b>Measuring principle</b>	<p>When a voltage is set between two electrodes in an electrolyte solution, the result is an electric field which exerts force on the charged ions: the positively charged cations move towards the negative electrode (cathode) and the negatively charged anions towards the positive electrode (anode). The ions, by way of capture or release of electrons at the electrodes, are discharged and so a current <math>I</math> flows through this cycle and the Ohms law <math>V = I \times R</math> applies. From the total resistance <math>R</math> of the current loop, only the resistance of the electrolyte solution, respectively its conductivity <math>1/R</math>, is of interest.</p> <p>The cell constant of the sensor is determined by the manufacturer and is printed on the sensor label. If the cell constant has been programmed in the transmitter, the instrument measures correctly. No calibration needs to be done, the sensor is factory-calibrated.</p>
<b>Temperature compensation</b>	<p>The mobility of ions in water increases with higher temperature, which enlarges the conductivity. Therefore, the temperature is measured simultaneously by an integrated Pt1000 temperature sensor and the conductivity is compensated to 25 °C.</p>
<b>Fluidics</b>	<p>The flow cell M-Flow PG consists of the flow cell block [B] and the calibration vessel [D]. The conductivity sensor [A] is fixed with a threaded sleeve.</p> <p>The sample enters at the sample inlet [F], flows through the deltaT flow sensor [C] (if installed) and then through the flow cell block into the calibration vessel [D], where the conductivity is measured.</p> <p>The sample leaves the calibration vessel via the flow cell block through sample outlet [E] and flows into the drain [G].</p>



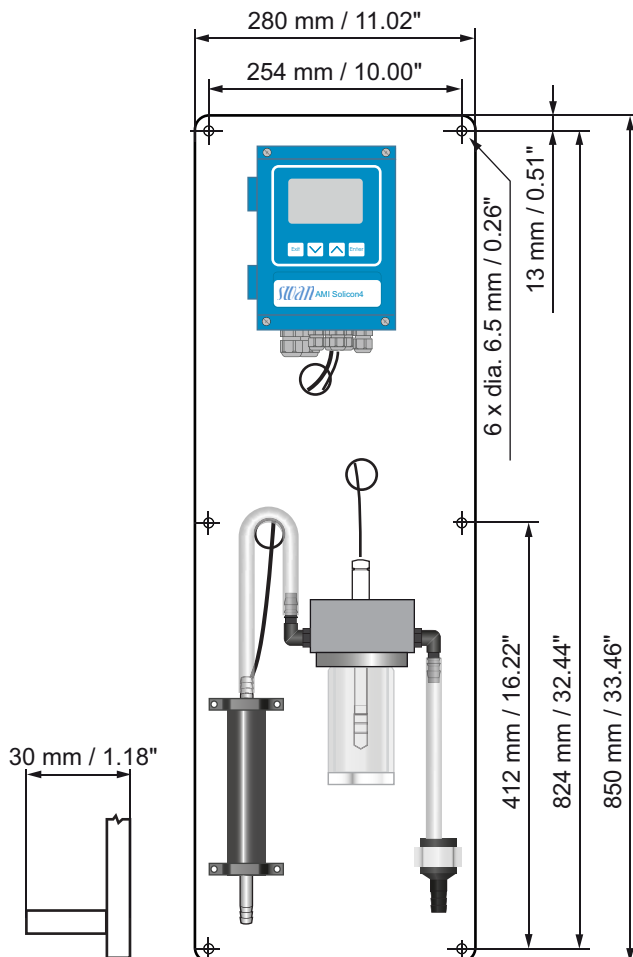
- |                                      |                        |
|--------------------------------------|------------------------|
| <b>A</b> Conductivity sensor         | <b>E</b> Sample outlet |
| <b>B</b> Flow cell block             | <b>F</b> Sample inlet  |
| <b>C</b> deltaT flow sensor (option) | <b>G</b> Drain         |
| <b>D</b> Calibration vessel          |                        |

## 2.2. Instrument Specification

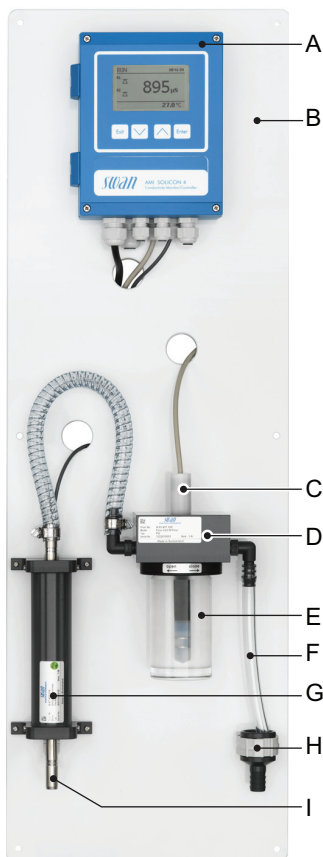
<b>Power Supply</b>	AC variant:	100–240 VAC ( $\pm 10\%$ ) 50/60 Hz ( $\pm 5\%$ )
	DC variant	10–36 VDC
	Power consumption:	max. 35 VA
<b>Transmitter specifications</b>	Housing:	aluminum, with a protection degree of IP 66 / NEMA 4X
	Ambient temperature:	–10 to +50 °C
	Storage and transport:	–30 to +85 °C
	Humidity:	10–90% rel., non condensing
	Display:	backlit LCD, 75 x 45 mm
<b>Sample requirements</b>	Flow rate:	4 to 15 l/h
	Temperature:	up to 50 °C
	Inlet pressure:	up to 1 bar
	Outlet pressure:	pressure free
<b>On-site requirements</b>	The analyzer site must permit connections to:	
	Sample inlet:	Flow cell with elbow hose nozzle 1/4" diam. 10 mm or deltaT sensor with hose nozzle diam. 10 mm
	Sample outlet:	1/2" hose nozzle for flexible tube diam. 20 x 15 mm
<b>Measuring Range</b>	Range	Resolution
	0.10 to 9.99 $\mu\text{S/cm}$	0.01 $\mu\text{S/cm}$
	10.0 to 99.9 $\mu\text{S/cm}$	0.1 $\mu\text{S/cm}$
	100 to 999 $\mu\text{S/cm}$	1 $\mu\text{S/cm}$
	1.00 to 9.99 mS/cm	0.01 mS/cm
	10.0 to 29.9 mS/cm	0.1 mS/cm
<b>Accuracy</b>	30 to 100 mS/cm	1 mS/cm
	$\pm 0.5\%$ of measured value	

**Dimensions**

Panel: PVC  
Dimensions: 280x850x150 mm  
Screws: 5 mm or 6 mm diameter  
Weight: 6.0 kg



## 2.3. Instrument Overview



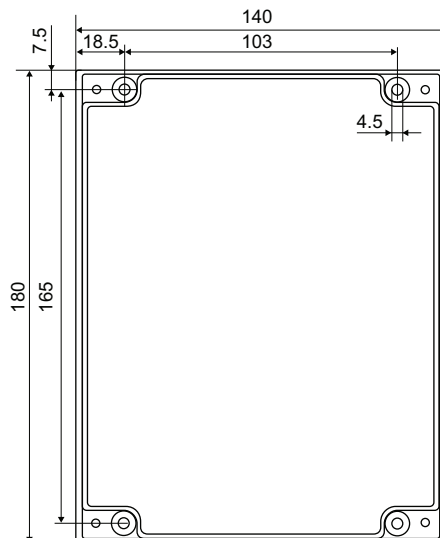
**A** Transmitter  
**B** Panel  
**C** Conductivity sensor  
**D** Flow cell block  
**E** Calibration vessel

**F** Sample outlet  
**G** DeltaT flow sensor (option)  
**H** Drain  
**I** Sample inlet

## 2.4. Single Components

### 2.4.1 AMI Solicon4 Transmitter

Electronic transmitter and controller for conductivity measurement.



#### Dimensions

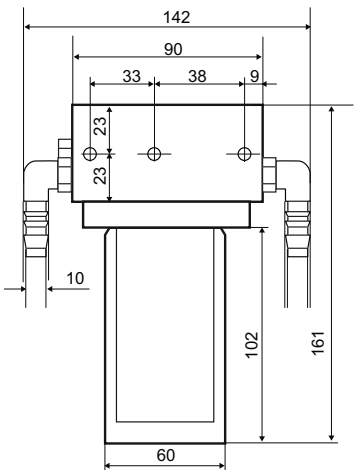
Width:	140 mm
Height:	180 mm
Depth:	70 mm
Weight:	1.5 kg

#### Specifications

Electronics case:	Cast aluminum
Protection degree:	IP 66 / NEMA 4X
Display:	backlit LCD, 75 x 45 mm
Electrical connectors:	screw clamps

2.4.2 Flow Cell M-Flow PG and M-Flow G1

- ♦ Flow cell M-Flow PG, made of PVC and acrylic glass with one 13.5 mm sensor opening for Swansensor Shurecon P.
- or
- ♦ Flow cell M-Flow G1, made of PVC and acrylic glass with one G 1" sensor opening for Swansensor Shurecon S.

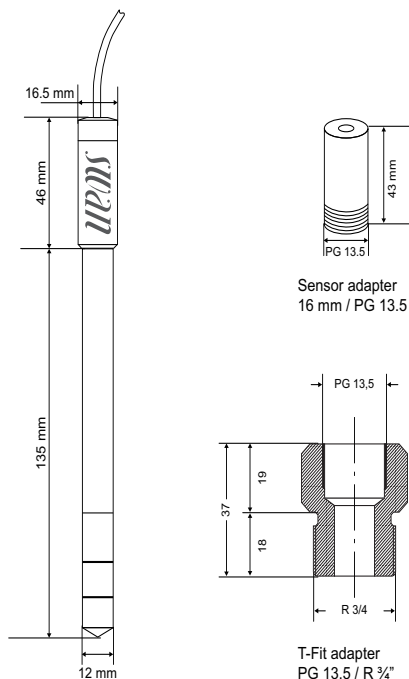


<b>Sample connections</b>	Inlet:	G 1/4" thread
	Outlet:	G 1/4" thread
<b>Sample conditions</b>	Each equipped with an elbow hose nozzle for 10 mm tube	
	Only valid for the flow cell without sensor.	
	Flow rate:	4 to 15 l/h
	Temperature:	up to 50 °C
	Inlet pressure:	up to 1 bar @ 25 °C
	Sample outlet:	Pressure-free outlet
	Particle size:	below 0.5 mm
<b>Dimensions</b>	No strong acids and bases.	
	No organic solvents.	
	Width:	90 to 142 mm
	Front-to-back:	105 mm
	Height:	161 mm
	Panel mounting:	3 screws M5



### 2.4.3 Swansensor Shurecon P

Sensor with integrated cable for the measurement of the specific conductivity. Four electrode design with platinum electrodes and built-in Pt1000 temperature sensor.

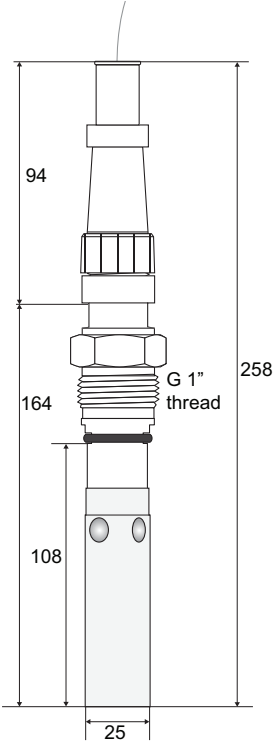


#### Specifications

Measuring range	0.1 $\mu\text{S}/\text{cm}$ to 100 $\text{mS}/\text{cm}$
Accuracy:	$\pm 1.5\%$ or $\pm 0.2 \mu\text{S}/\text{cm}$ , whichever is greater
Temperature sensor:	Pt1000
Operating conditions:	$> 50^\circ\text{C}$ Max. temperature short-time $90^\circ\text{C}$ Max. pressure 10 bar at $25^\circ\text{C}$ .
Electrical connection:	Sensor with integrated cable
Process connection:	PG 13.5 mm

2.4.4 Swansensor Shurecon S

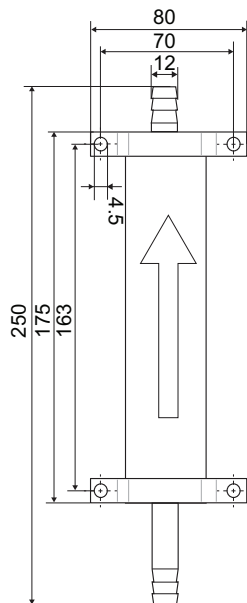
Sensor for the measurement of the specific conductivity. Four-electrode design with integrated Pt1000 temperature sensor. Screw connector with cable must be ordered separately.



Specifications	Measuring range	0.1 $\mu\text{S}/\text{cm}$ to 100 $\text{mS}/\text{cm}$
	Accuracy:	$\pm 1\%$ or $\pm 0.2\ \mu\text{S}/\text{cm}$ whichever is greater
	Temperature sensor:	Pt1000
	Operating conditions:	Max. temperature: 120 $^{\circ}\text{C}$ at 6.5 bar Max. pressure: 12 bar at 20 $^{\circ}\text{C}$ Sterilizable at: 120 $^{\circ}\text{C}$ / 5 bar / 30 min
	Electrical connection:	Plug M16 male (IP 67)
	Process connection:	G 1" thread
	Space around sensor tip:	20 mm

### 2.4.5 Swansensor DeltaT

Calorimetric flow meter based on heat dissipation. For applications in potable water, surface water treatment and effluent.



<b>Specifications</b>	Measuring range/Flow rate	0–40 l/h
	Accuracy:	± 20 %
	Response time $t_{90}$ :	ca. 1 min
	Sample temperature:	5–35 °C
	Sample inlet and outlet:	for tubing diam. 10–11 mm
	Max. cable length:	1 m

## 3. Installation

### 3.1. Installation Checklist Monitors

<b>On site requirements</b>	AC variant: 100–240 VAC ( $\pm 10\%$ ), 50/60 Hz ( $\pm 5\%$ ) DC variant: 10–36 VDC Power consumption: 35 VA maximum. Protective earth connection required. Sample line with sufficient sample flow and pressure (see <a href="#">Instrument Specification</a> , p. 12).
<b>Installation</b>	Mount the instrument in vertical position. Display should be at eye level. Connect sample and waste.
<b>Electrical Wiring</b>	Connect all external devices like limit switches, current loops and pumps. Connect power cord; do not switch on power yet!
<b>Power-up</b>	Turn on the sample flow and wait until the flow cell is completely filled. Switch on power.
<b>Instrument set-up</b>	Adjust sample flow. Program all parameters for sensor and external devices (interface, recorders, etc.). Program all parameters for instrument operation (limits, alarms).
<b>Run-in period</b>	Let the instrument run continuously for 1 h.
<b>Calibration</b>	Perform a calibration if necessary, see <a href="#">Calibration</a> , p. 44.

### 3.2. Mounting of Instrument Panel

To mount the instrument panel proceed according the following list:

- The instrument must only be installed by trained personnel.
- Mount the instrument in vertical position.
- For ease of operation mount it so that the display is at eye level.
- For the installation a kit containing the following installation material is available:
  - 6 Screws 6x60 mm
  - 6 Dowels
  - 6 Washers 6.4/12 mm

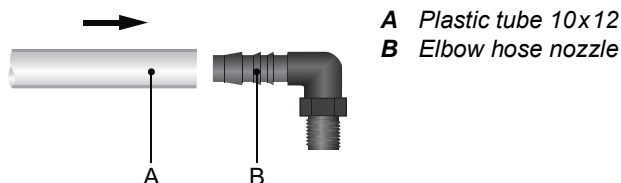
#### Mounting requirements

The instrument is only intended for indoor installation, dimensions see [Dimensions, p. 13](#).

### 3.3. Connecting Sample Inlet and Outlet

#### Sample inlet

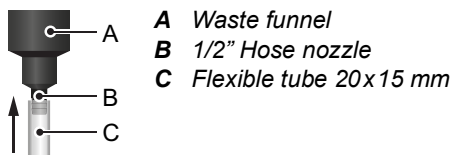
Use a plastic tube (FEP, PA, or PE 10x12 mm) to connect the sample inlet at the flow cell.



If a deltaT sensor is installed, push the plastic tube over the hose nozzle of the deltaT sensor.

#### Sample outlet

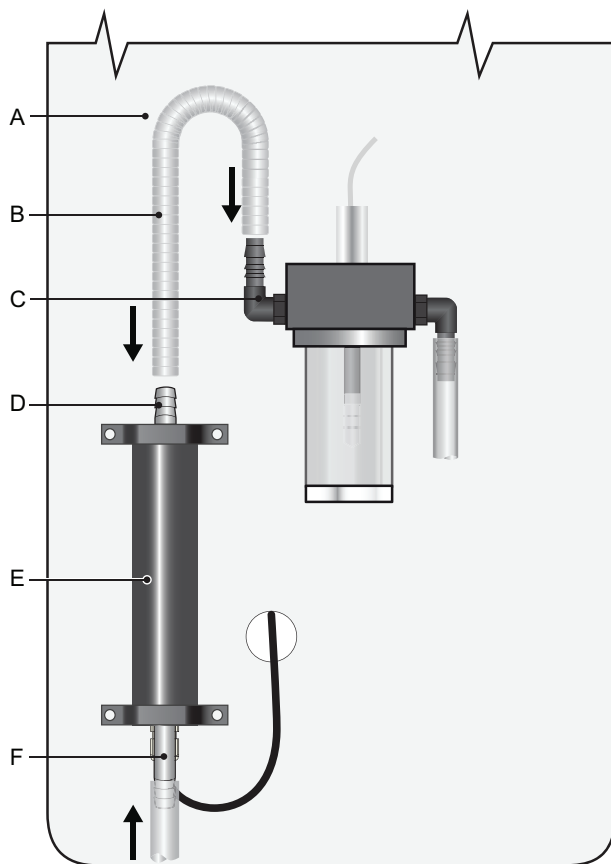
Connect the flexible tube 20x15 mm [C] to the 1/2" hose nozzle [B] and place it into a drain with atmospheric pressure.



### 3.4. Install Swansensor deltaT (Option)

The following description assumes that the installation of the deltaT sensor takes place after commissioning of the monitor.

Install the deltaT sensor in vertical position with the sample inlet [F] and cable gland facing downwards. To ensure laminar flow, the sample inlet must not be restricted; e.g. by a fitting that creates turbulences.



- |                            |  |
|----------------------------|--|
| <b>A</b> Panel             | <b>D</b> Hose nozzle at deltaT sensor outlet |
| <b>B</b> Tube connection   | <b>E</b> deltaT sensor                       |
| <b>C</b> Elbow hose nozzle | <b>F</b> Hose nozzle at deltaT sensor inlet  |

### **3.4.1 Mount the deltaT Sensor and Connect the Sample Inlet**

- 1** Stop operation according to chapter [Stop of Operation for Maintenance, p. 42](#).
- 2** Mount the deltaT sensor [E] in vertical position to the panel [A].
- 3** Remove the plastic tube from the elbow hose nozzle at the flow cell.
- 4** Connect the plastic tube to the hose nozzle [F] of the deltaT sensor inlet.
- 5** Rotate the elbow hose nozzle of the flow cell by 180 degrees.
- 6** Install the hose connection [B] enclosed in the installation kit, from the hose nozzle [D] at the deltaT sensor outlet to the elbow hose nozzle [C].



### 3.4.2 Connect the Sensor Cable to the Transmitter

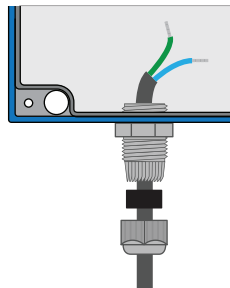
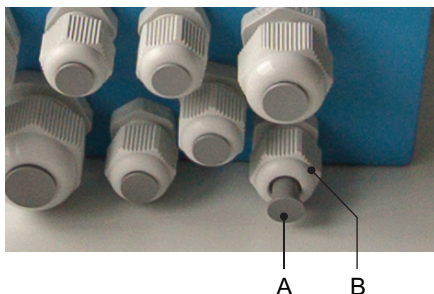


#### **WARNING**

##### **Risk of electrical shock.**

Do not perform any work on electrical components if the transmitter is switched on. Failure to follow safety instructions can result in serious injury or death.

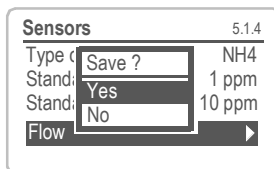
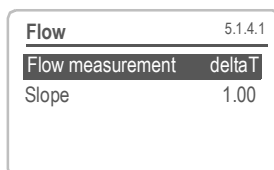
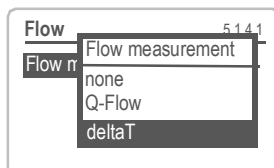
Make sure the power specification of the instrument corresponds to the power on site.



- 1 Remove the plug [A] from the cable gland [B]
- 2 Open the AMI transmitter housing.
- 3 Feed the sensor cable through the cable gland [B] into the transmitter housing.
- 4 Connect the cable to the terminals according to the connecting diagram see [Connection Diagram, p. 29](#).
- 5 Close the AMI transmitter housing.
- 6 Switch on power.



### 3.4.3 Change Firmware Settings



- 1 Navigate to <Installation> <Sensors> <Flow> <Flow measurement>.
- 2 Press [Enter]
- 3 Select <deltaT>
- 4 Press [Enter]
- 5 Press 2 x [Exit]
- 6 Press [Enter] to confirm with Yes
- 7 Press [Exit] until the display shows the measuring values.

### 3.4.4 Adjust the deltaT sensor

The deltaT flow sensor is factory calibrated at 20 °C ( $\pm 20\%$  accuracy).

The accuracy of the flow measurement depends on the ambient temperature of the location where the deltaT sensor is installed. If the ambient temperature is higher or lower than 20 °C, the deltaT flow sensor can be adjusted. If an adjustment of the deltaT sensor is necessary proceed as follows:

**Run in** After installation let the sensor run-in for at least 1h.

**Determine the  
flow rate**

- 1 Put the sample outlet of the instrument for 10 min. into a measuring cup with a sufficient volume.
- 2 To get the flow rate in l/h, multiply the amount of water contained in the measuring cup with factor 6.  
*⇒ The flow rate in l/h results from the multiplication of the amount of water after 10 min by 6.*

**Adjust slope**

- 1 Navigate to <Installation/Sensors/Flow>, choose <Slope> and press [Enter].
- 2 If the calculated flow rate is higher than the displayed flow rate increase the Slope value.
- 3 If the calculated flow rate is lower than the displayed flow rate decrease the Slope value.
- 4 Press [Exit] and save with [Enter].
- 5 Compare the calculated flow rate with the displayed flow rate.  
*⇒ If the flow rates are roughly equal, the adjustment is finished.*  
♦ Else repeat steps 1 to 5.

### 3.5. Electrical Connections



#### WARNING

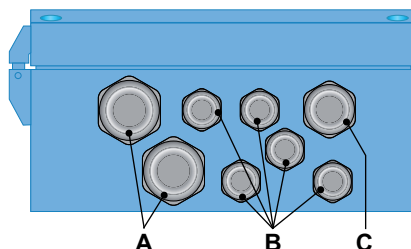
##### Risk of electrical shock.

Do not perform any work on electrical components if the transmitter is switched on. Failure to follow safety instructions can result in serious injury or death.

- ♦ Always turn off power before manipulating electric parts.
- ♦ Grounding requirements: Only operate the instrument from a power outlet which has a ground connection.
- ♦ Make sure the power specification of the instrument corresponds to the power on site.

#### Cable thicknesses

In order to comply with IP66, use the following cable thicknesses



**A** PG 11 cable gland: cable  $\varnothing_{outer}$  5–10 mm

**B** PG 7 cable gland: cable  $\varnothing_{outer}$  3–6.5 mm

**C** PG 9 cable gland: cable  $\varnothing_{outer}$  4–8 mm

**Note:** Protect unused cable glands

#### Wire

- ♦ For Power and Relays: Use max. 1.5 mm<sup>2</sup> / AWG 14 stranded wire with end sleeves.
- ♦ For Signal Outputs and Input: Use 0.25 mm<sup>2</sup> / AWG 23 stranded wire with end sleeves.



**WARNING**

**External Voltage.**

External supplied devices connected to relay 1 or 2 or to the alarm relay can cause electrical shocks.

- ♦ Make sure that the devices connected to the following contacts are disconnected from the power before resuming installation.
  - relay 1
  - relay 2
  - alarm relay



**WARNING**

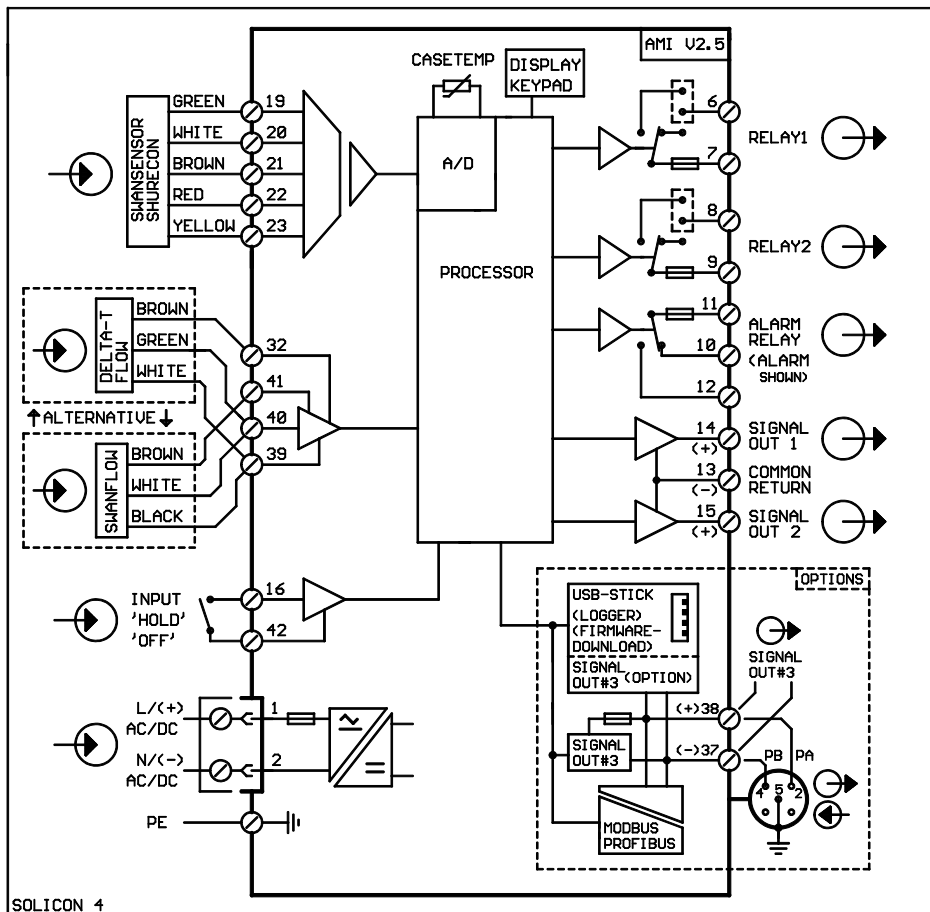
To prevent from electrical shock, do not connect the instrument to the power unless the ground wire (PE) is connected.



**WARNING**

The mains of the AMI Transmitter must be secured by a main switch and appropriate fuse or circuit breaker.

### 3.5.1 Connection Diagram



#### CAUTION

Use only the terminals shown in this diagram, and only for the mentioned purpose. Use of any other terminals will cause short circuits with possible corresponding consequences to material and personnel.

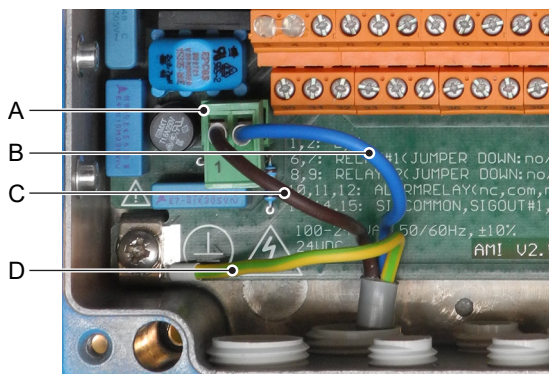
### 3.5.2 Power Supply



#### WARNING

##### Electrical shock hazard

Installation and maintenance of electrical parts must be performed by professionals. Always turn off power before manipulating electric parts.



- A** Power supply connector
- B** Neutral conductor, Terminal 2
- C** Phase conductor, Terminal 1
- D** Protective earth PE

**Note:** The protective earth wire (Ground) has to be connected to the grounding terminal.

#### Installation requirements

The installation must meet the following requirements.

- ♦ Mains cable to comply with standards IEC 60227 or IEC 60245; flammable rating FV1
- ♦ Mains equipped with an external switch or circuit-breaker
  - near the instrument
  - easily accessible to the operator
  - marked as interrupter for AMI Solicon4

### 3.6. Relay Contacts

#### 3.6.1 Input

**Note:** Use only potential-free (dry) contacts.  
The total resistance (sum of cable resistance and resistance of the relay contact) must be less than 50  $\Omega$ .

Terminals 16/42  
For programming see [Program List and Explanations, p. 55](#).

#### 3.6.2 Alarm Relay

**Note:** Max. load 1 A/250 VAC  
Alarm output for system errors.  
Error codes see [Troubleshooting, p. 46](#).

**Note:** With certain alarms and certain settings of the AMI transmitter the alarm relay does not switch. The error, however, is shown on the display.

	Terminals	Description	Relay connection
<b>NC</b> <sup>1)</sup> Normally Closed	10/11	Active (opened) during normal operation. Inactive (closed) on error and loss of power.	
<b>NO</b> Normally Open	12/11	Active (closed) during normal operation. Inactive (opened) on error and loss of power.	


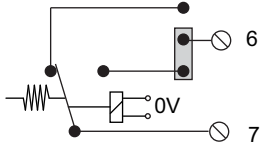

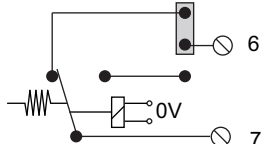
1) usual use

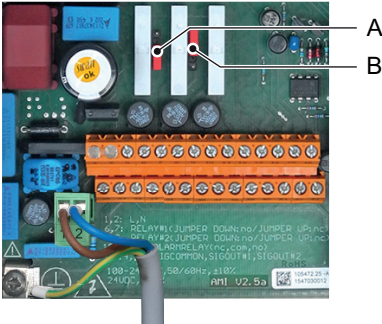
3.6.3 Relay Contacts 1 and 2

**Note:** Rated load 1 AT / 250 VAC

Relay 1 and 2 can be configured as normally open or as normally closed. Standard for both relays is normally open. To configure a Relay as normally closed, set the jumper in the upper position.

**Note:** Some error codes and the instrument status may influence the status of the relays described below.

Relay config.	Terminals	Jumper pos.	Description	Relay configuration
Normally Open	6/7: Relay 1 8/9: Relay 2		Inactive (opened) during normal operation and loss of power. Active (closed) when a programmed function is executed.	
Normally Closed	6/7: Relay 1 8/9: Relay 2		Inactive (closed) during normal operation and loss of power. Active (opened) when a programmed function is executed.	



- A Jumper set as normally open (standard setting)
- B Jumper set as normally closed

For programming see Menu Installation [Program List and Explanations](#), p. 55.





## CAUTION

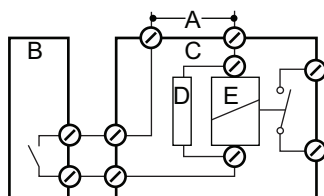
### Risk of damage of the relays in the AMI Transmitter due to heavy inductive load.

Heavy inductive or directly controlled loads (solenoid valves, dosing pumps) may destroy the relay contacts.

- To switch inductive loads > 0.1 A use an AMI relay box available as an option or suitable external power relays.

## Inductive load

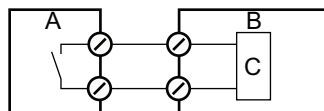
Small inductive loads (max 0.1 A) as for example the coil of a power relay can be switched directly. To avoid noise voltage in the AMI Transmitter it is mandatory to connect a snubber circuit in parallel to the load.



- A** AC or DC power supply
- B** AMI Transmitter
- C** AMI Relay box
- D** Snubber
- E** Power relay coil

## Resistive load

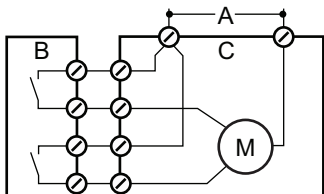
Resistive loads (max. 1 A) and control signals for PLC, impulse pumps and so on can be connected without further measures



- A** AMI Transmitter
- B** PLC or controlled pulse pump
- C** Logic

## Actuators

Actuators, like motor valves, are using both relays: One relay contact is used for opening, the other for closing the valve, i.e. with the 2 relay contacts available, only one motor valve can be controlled. Motors with loads bigger than 0.1 A must be controlled via external power relays or an AMI relay box.



- A** AC or DC power supply
- B** AMI Transmitter
- C** Actuator

## 3.7. Signal Outputs

### 3.7.1 Signal Output 1 and 2 (current outputs)

**Note:** Max. burden 510  $\Omega$ .

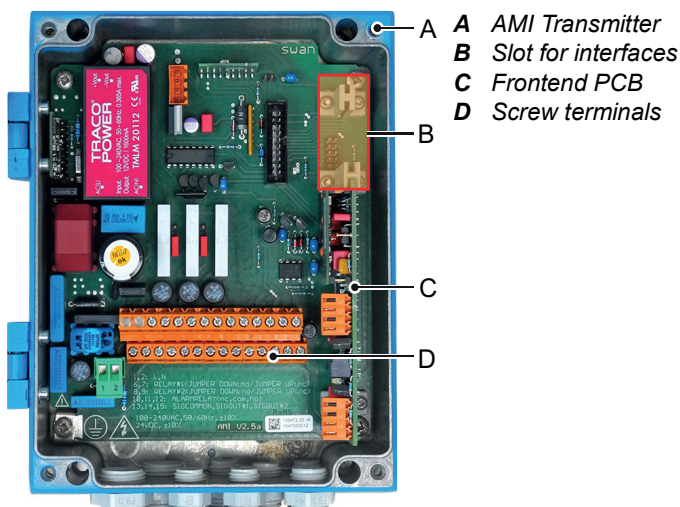
*If signals are sent to two different receivers, use signal isolator (loop isolator).*

Signal output 1: Terminals 14 (+) and 13 (-)

Signal output 2: Terminals 15 (+) and 13 (-)

For programming see [Program List and Explanations, p. 55](#), Menu Installation

## 3.8. Interface Options



The slot for interfaces can be used to expand the functionality of the AMI instrument with either:

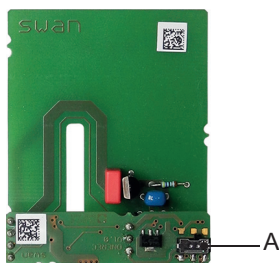
- ♦ a third signal output
- ♦ a Profibus or Modbus connection
- ♦ a HART connection
- ♦ a USB Interface

### 3.8.1 Signal Output 3

Terminals 38 (+) and 37 (-).

Requires the additional board for the third signal output 0/4–20 mA. The third signal output can be operated as a current source or as a current sink (switchable via switch [A]). For detailed information see the corresponding installation instruction.

**Note:** Max. burden 510  $\Omega$ .



Third signal output 0/4–20 mA PCB

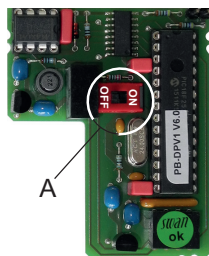
A Operating mode selector switch

### 3.8.2 Profibus, Modbus Interface

Terminal 37 PB, Terminal 38 PA

To connect several instruments by means of a network or to configure a PROFIBUS DP connection, consult the PROFIBUS manual. Use appropriate network cable.

**Note:** The switch must be ON, if only one instrument is installed, or on the last instrument in the bus.



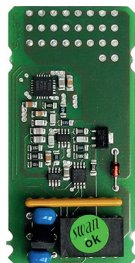
Profibus, Modbus Interface PCB (RS 485)

A On - OFF switch

### 3.8.3 HART Interface

Terminals 38 (+) and 37 (-).

The HART interface PCB allows for communication via the HART protocol. For detailed information, consult the HART manual.

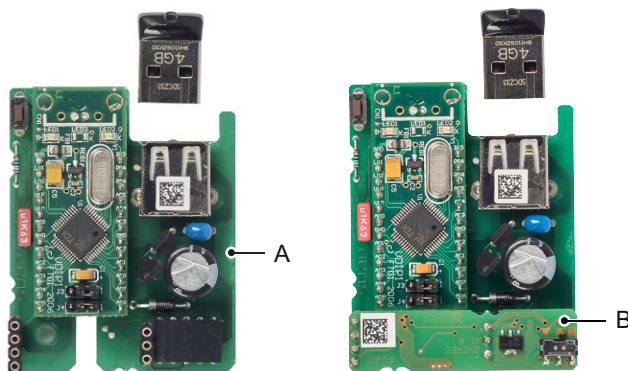


HART Interface PCB

### 3.8.4 USB Interface

The USB Interface is used to store Logger data and for Firmware upload. For detailed information see the corresponding installation instruction.

The optional third signal output 0/4–20 mA PCB [B] can be plugged onto the USB interface and used in parallel.



USB Interface

*A* USB interface PCB

*B* Third signal output 0/4 - 20 mA PCB

## 4. Instrument Setup

### 4.1. Establish Sample Flow

- 1 Open sample flow tap.
- 2 Wait until the flow cell is completely filled.
- 3 Switch on power.

### 4.2. Programming

#### Programming

The sensor characteristics are printed on the label of the sensor.

Program all sensor parameters in Menu 5.1.1.1,  
<Installation> <Sensors> <Sensor parameters>:

SW-xx-xx-xx	ZK = 0.0417	Cell constant
SWAN AG		Temperature correction

Enter the:

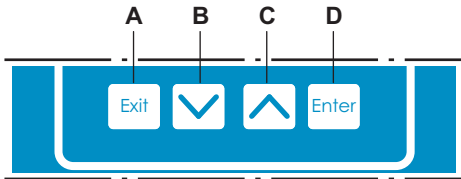
- ♦ Cell constant [ $\text{cm}^{-1}$ ]
- ♦ Temperature correction [ $^{\circ}\text{C}$ ]
- ♦ Cable length

**Note:** *Cable length [m] Set the cable length to 0.0 m if the sensors are installed in the flow cell on the AMI monitor.*

Program all parameters for external devices (interface, recorders, etc.) and for instrument operation (limits, alarms). See [Program List and Explanations, S. 55](#).

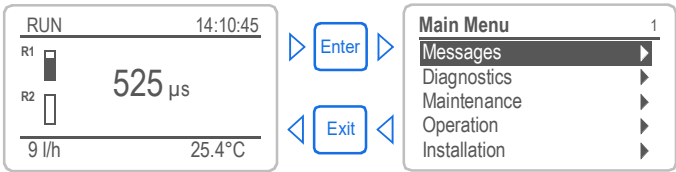
# 5. Operation

## 5.1. Keys

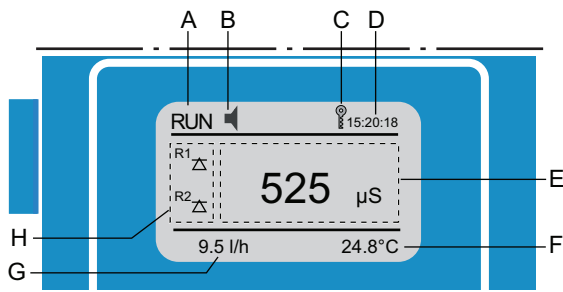


- A** to exit a menu or command (rejecting any changes)  
to move back to the previous menu level
- B** to move DOWN in a menu list and to decrease digits
- C** to move UP in a menu list and to increase digits
- D** to open a selected sub-menu  
to accept an entry

### Program Access, Exit



## 5.2. Display



- A** RUN normal operation  
 HOLD input closed or cal delay: Instrument on hold (shows status of signal outputs).  
 OFF input closed: control/limit is interrupted (shows status of signal outputs).
- B** ERROR Error Fatal Error
- C** Keys locked, transmitter control via Profibus
- D** Time
- E** Process values
- F** Sample temperature
- G** Sample flow
- H** Relay status

### Relay status, symbols

- upper/lower limit not yet reached  
 upper/lower limit reached  
 control upw./downw. no action  
 control upw./downw. active, dark bar indicates control intensity
- motor valve closed  
 motor valve: open, dark bar indicates approx. position
- timer  
 timer: timing active (hand rotating)

5.3. Software Structure

Main Menu	1
Messages	▶
Diagnostics	▶
Maintenance	▶
Operation	▶
Installation	▶

Messages	1.1
Pending Errors	▶
Message List	▶

Menu **Messages 1**

Reveals pending errors as well as an event history (time and state of events that have occurred at an earlier point of time).  
It contains user relevant data.

Diagnostics	2.1
Identification	▶
Sensors	▶
Sample	▶
I/O State	▶
Interface	▶

Menu **Diagnostics 2**

Provides user relevant instrument and sample data.

Maintenance	3.1
Calibration	▶
Process Cal.	▶
Simulation	▶
Set Time	23.09.06 16:30:00

Menu **Maintenance 3**

For instrument calibration, relay and signal output simulation, and to set the instrument time.  
It is used by the service personnel.

Operation	4.1
Sensors	▶
Relay Contacts	▶
Logger	▶

Menu **Operation 4**

User relevant parameters that might need to be modified during daily routine. Normally password protected and used by the process operator.  
Subset of menu 5 - Installation, but process-related.

Installation	5.1
Sensors	▶
Signal Outputs	▶
Relay Contacts	▶
Miscellaneous	▶
Interface	▶

Menu **Installation 5**

For initial instrument set up by SWAN authorized person, to set all instrument parameters. Can be protected by means of password.



## 5.4. Changing Parameters and values

### Changing parameters

The following example shows how to change the logger interval:

Logger 4.4.1  
Log interval 30 min  
Clear logger no

Logger 4.1.3  
Log inter Interval.  
Clear log 5 min  
10 min  
30 min  
1 Hour

Logger 4.1.3  
Log interval 10 min  
Clear logger no

Logger 4.1.3  
Log inter Save ?  
Clear log Yes  
No

- 1 Select the parameter you want to change.
- 2 Press [Enter]
- 3 Press [▲] or [▼] key to highlight the required parameter.
- 4 Press [Enter] to confirm the selection or [Exit] to keep the previous parameter).

⇒ The selected parameter is highlighted but not saved yet.

- 5 Press [Exit].

⇒ Yes is highlighted.

- 6 Press [Enter] to save the new parameter.  
⇒ The system reboots, the new parameter is set.

### Changing values

Alarm Conductivity 5.3.1.1.1  
Alarm High 300 mS  
Alarm Low 0.00 µS  
Hysteresis 1.00 µS  
Delay 5 Sec

Alarm Conductivity 5.3.1.1.1  
Alarm High 120 mS  
Alarm Low 0.00 µS  
Hysteresis 1.00 µS  
Delay 5 Sec

- 1 Select the value you want to change.
- 2 Press [Enter].
- 3 Set required value with [▲] or [▼] key.
- 4 Press [Enter] to confirm the new value.
- 5 Press [Exit].  
⇒ Yes is highlighted.
- 6 Press [Enter] to save the new value.

## 6. Maintenance

### 6.1. Maintenance Schedule

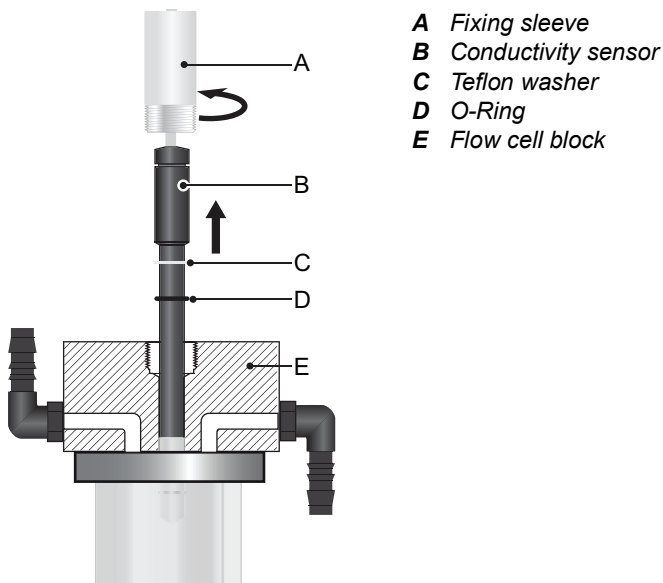
Preventive maintenance frequency depends on water quality, on the application, and on national regulations.

Monthly	♦ Check sample flow.
If required	♦ Clean conductivity sensor ♦ Perform a calibration

### 6.2. Stop of Operation for Maintenance

- 1 Stop sample flow.
- 2 Shut off power of the instrument.

## 6.3. Maintenance of the Sensor



### 6.3.1 Remove the Sensor from the Flow Cell

To remove the sensor from the flow cell proceed as follows:

- 1 Unscrew and remove the fixing sleeve [A].
- 2 Pull the conductivity sensor [B] out of the flow cell block [E].

#### **Cleaning**

If the sensor is contaminated, take a small brush and clean it with water and detergents.

In case of heavy contamination with oil or grease, use ethanol to clean it. Take a soft tissue and clean the tip of the sensor cautiously. After each cleaning, the sensor must be rinsed with clean water.

### 6.3.2 Install the Sensor into the Flow Cell

- 1 Make sure that the washer [C] and the O-ring [D] are in correct position.
- 2 Push the sensor through the flow cell block [E] into the flow cell.
- 3 Tighten the fixing sleeve [A] to fix the sensor.

## 6.4. Calibration

Since the sensor is very reliable a calibration is usually not necessary. A calibration is recommended if:

- ♦ the cell constant is not known
- ♦ the sensor is contaminated
- ♦ the maintenance measurement shows a discrepancy.

### Reagent for the Calibration:

Calibration solution 1.413 mS/cm (25 °C) 1000 ml. Prepare according to DIN 38404 / ISO 7888: 1985 / EN 27888.

- 1 Stop the sample flow.
- 2 Navigate to menu <Maintenance> / <Calibration>.
- 3 Press [Enter] and follow the dialog on the Display.
- 4 Remove the sensor from the flow cell.
- 5 Clean the sensor carefully and rinse it with clean water, see [Maintenance of the Sensor, p. 43](#).
- 6 Use a beaker and fill it with one liter calibration solution.  
⇒ *The beaker's diameter must be large enough to allow a distance of at least 3 cm between the sensor and the edge of the beaker.*
- 7 Put the sensor into the beaker filled with calibration solution.

Calibration	3.1.5
Clean the sensor and place it in standard solution	
-----	
[Enter] to continue	

Calibration	3.1.5
Sensor must have a min. distance of 3 cm from the beakers edge	
-----	
[Enter] to continue	

Calibration	3.1.1
Standard solution	1.41 mS
Current Value	10.07 µS
Cell constant	0.406 cm <sup>-1</sup>
-----	
Progress	<div style="width: 50%;"></div>

- 8 Wait at least 5 minutes to permit temperature equilibration between sensor and calibration solution.
- 9 Start the calibration procedure.

- 10 Press [Enter], to save the values if the calibration was successful.
- 11 Install the sensor into the flow cell.

## **6.5. Longer Stop of Operation**

- 1** Stop sample flow.
- 2** Shut off power of the instrument.
- 3** Remove the sensor from the flow cell and dry it with a soft tissue.
- 4** Empty and dry the flow cell.

## 7. Troubleshooting

### 7.1. Error List

#### Error

Non-fatal Error. Indicates an alarm if a programmed value is exceeded.

Such Errors are marked **E0xx**.

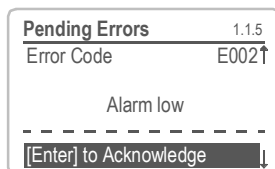
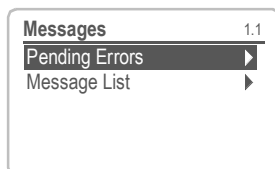
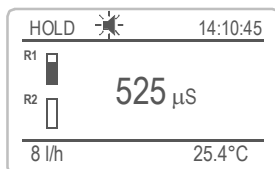
#### Fatal Error (blinking symbol)

Control of dosing devices is interrupted.

The indicated measured values are possibly incorrect.

Fatal Errors are divided in the following two categories:

- ♦ Errors which disappear if correct measuring conditions are recovered (i.e. Sample Flow low).  
Such Errors are marked **E0xx**
- ♦ Errors which indicate a hardware failure of the instrument.  
Such Errors are marked **E0xx**



#### Error or fatal Error

Error not yet acknowledged.

Check **Pending Errors 1.1.5** and take corrective action.

Navigate to menu <Messages>/<Pending Errors>.

Press [ENTER] to acknowledge the Pending Errors.

⇒ *The Error is reset and saved in the Message List.*

Error	Description	Corrective action
<b>E001</b>	Cond. Alarm high	<ul style="list-style-type: none"> <li>– check process</li> <li>– check programmed value, see <a href="#">5.3.1.1, p. 64</a></li> </ul>
<b>E002</b>	Cond. Alarm low	<ul style="list-style-type: none"> <li>– check process</li> <li>– check programmed value, see <a href="#">5.3.1.1, p. 64</a></li> </ul>
<b>E003</b>	Conc. Alarm high	<ul style="list-style-type: none"> <li>– check process</li> <li>– check programmed value, see <a href="#">5.3.1.5, p. 66</a></li> </ul>
<b>E004</b>	Conc. Alarm low	<ul style="list-style-type: none"> <li>– check process</li> <li>– check programmed value, see <a href="#">5.3.1.5, p. 66</a></li> </ul>
<b>E007</b>	Sample Temp. high	<ul style="list-style-type: none"> <li>– check process</li> <li>– check programmed value, see <a href="#">5.3.1.3, p. 65</a></li> </ul>
<b>E008</b>	Sample Temp. low	<ul style="list-style-type: none"> <li>– check process</li> <li>– check programmed value, see <a href="#">5.3.1.3, p. 65</a></li> </ul>
<b>E009</b>	Sample Flow high	<ul style="list-style-type: none"> <li>– check sample inlet pressure</li> <li>– check programmed value, see <a href="#">5.3.1.2.2, p. 65</a></li> </ul>
<b>E010</b>	Sample Flow low	<ul style="list-style-type: none"> <li>– check sample inlet pressure</li> <li>– Check flow regulating valve</li> <li>– check programmed value, see <a href="#">5.3.1.2.35, p. 65</a></li> </ul>
<b>E011</b>	Temp. shorted	<ul style="list-style-type: none"> <li>– Check wiring of sensor</li> </ul>
<b>E012</b>	Temp. disconnected	<ul style="list-style-type: none"> <li>– Check wiring of sensor</li> </ul>
<b>E013</b>	Case Temp. high	<ul style="list-style-type: none"> <li>– check case/environment temperature</li> <li>– check programmed value, see <a href="#">5.3.1.4.1, p. 65</a></li> </ul>
<b>E014</b>	Case Temp. low	<ul style="list-style-type: none"> <li>– check case/environment temperature</li> <li>– check programmed value, see <a href="#">5.3.1.4.2, p. 65</a></li> </ul>

Error	Description	Corrective action
<b>E017</b>	Control time-out	– Check control device or programming in Installation, Relay contact, Relay 1/2 <a href="#">5.3.2</a> and <a href="#">5.3.3</a> , p. 66
<b>E018</b>	Temp. out of Table	– Check sample temperature
<b>E019</b>	Conc. out of Table	–
<b>E024</b>	Input active	– See If Fault Yes is programmed in Menu see <a href="#">5.3.4</a> , p. 70
<b>E026</b>	IC LM75	– call service
<b>E028</b>	Signal output open	– Check wiring on signal outputs 1 and 2
<b>E030</b>	EEProm Frontend	– call service
<b>E031</b>	Cal. Recout	– call service
<b>E032</b>	Wrong Frontend	– call service
<b>E033</b>	Power-on	– none, normal status
<b>E034</b>	Power-down	– none, normal status



## 7.2. Replacing Fuses



### WARNING

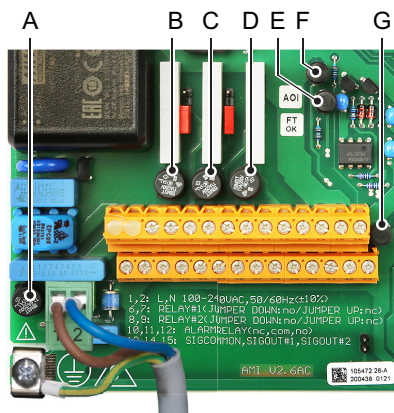
#### External Voltage.

External supplied devices connected to relay 1 or 2 or to the alarm relay can cause electrical shocks.

- Make sure that the devices connected to the following contacts are disconnected from the power before resuming installation.
  - relay 1
  - relay 2
  - alarm relay

When a fuse has blown, find out the cause and fix it before replacing it with a new one.

Use tweezers or needle-nosed pliers to remove the defective fuse. Use original fuses provided by SWAN only.



- A** AC variant: 1.6 AT/250 V Instrument power supply  
DC variant: 3.15 AT/250 V Instrument power supply
- B** 1.0 AT/250V Relay 1
- C** 1.0 AT/250V Relay 2
- D** 1.0 AT/250V Alarm relay
- E** 1.0 AF/125V Signal output 2
- F** 1.0 AF/125V Signal output 1
- G** 1.0 AF/125V Signal output 3

## 8. Program Overview

For explanations about each parameter of the menus see [Program List and Explanations, p. 55](#).

- ♦ Menu 1 **Messages** informs about pending errors and maintenance tasks and shows the error history. Password protection possible. No settings can be modified.
- ♦ Menu 2 **Diagnostics** is always accessible for everybody. No password protection. No settings can be modified.
- ♦ Menu 3 **Maintenance** is for service: Calibration, simulation of outputs and set time/date. Please protect with password.
- ♦ Menu 4 **Operation** is for the user, allowing to set limits, alarm values, etc. The presetting is done in the menu Installation (only for the System engineer). Please protect with password.
- ♦ Menu 5 **Installation**: Defining assignment of all inputs and outputs, measuring parameters, interface, passwords, etc. Menu for the system engineer. Password strongly recommended.

### 8.1. Messages (Main Menu 1)

Pending Errors	Pending Errors	1.1.5*	* Menu numbers
1.1*			
Message List	Number	1.2.1*	
1.2*	Date, Time		

8.2.   Diagnostics (Main Menu 2)

<b>Identification</b>	Designation	AMI Solicon4		* Menu numbers
2.1*	Version	V6.20-09/16		
	<b>Factory Test</b>	<i>Instrument</i>	2.1.3.1*	
	2.1.3*	<i>Motherboard</i>		
		<i>Front End</i>		
	<b>Operating Time</b>	<i>Years / Days / Hours / Minutes / Seconds</i>	2.1.4.1*	
	2.1.4*			
<b>Sensors</b>	<b>Cond. Sensor</b>	<i>Current value</i>		
2.2*	2.2.1*	<i>Raw value</i>		
		<i>Cell constant</i>		
		<i>Contamination</i>		
		<b>Cal. History</b>	<i>Number,</i>	2.2.1.5.1*
		2.2.1.5*	<i>Date, Time</i>	
			<i>Cell Constant</i>	
	<b>Miscellaneous</b>	<i>Case Temp.</i>	2.2.2.1*	
	2.2.2*			
<b>Sample</b>	<i>Sample ID</i>	2.3.1*		
2.3*	<i>Temperature</i>	°C		
	<i>(Pt1000)</i>	Ohm		
	<i>Sample Flow</i>	l/h		
	<i>Raw value</i>	Hz	<i>if Q-Flow</i>	
	<i>DeltaT 1</i>	°C	<i>It deltaT sensor</i>	
	<i>DeltaT2</i>	°C	<i>It deltaT sensor</i>	
<b>I/O State</b>	<i>Alarm Relay</i>	2.4.1*		
2.4*	<i>Relay 1 and 2</i>	2.4.2*		
	<i>Input</i>			
	<i>Signal Output 1 and 2</i>			
<b>Interface</b>	<i>Protocol</i>	2.5.1*		(only with RS485
2.5*	<i>Baud rate</i>			Interface)

8.3. Maintenance (Main Menu 3)

Calibration	Follow instructions	3.1.5*	*Menu numbers
3.1*			
Simulation	Alarm Relay	3.3.1*	
3.2*	Relay 1	3.3.2*	
	Relay 2	3.3.3*	
	Signal Output 1	3.3.4*	
	Signal Output 2	3.3.5*	
Set Time	(Date), (Time)		
3.3*			

8.4. Operation (Main Menu 4)

Sensors	Filter Time Const.	4.1.1*		
4.1*	Hold after Cal	4.1.2*		
Relay Contacts	Alarm Relay	Alarm Conductivity	Alarm High	4.2.1.1.1*
4.2*	4.2.1*	4.2.1.1*	Alarm Low	4.2.1.1.25*
			Hysteresis	4.2.1.1.35*
			Delay	4.2.1.1.45*
	If concentration	Alarm Concentration	Alarm High	4.2.1.2.1*
	is chosen	4.2.1.2*	Alarm Low	4.2.1.2.25*
			Hysteresis	4.2.1.2.35*
			Delay	4.2.1.2.45*
	Relay 1/2	Setpoint	4.2.x.100*	
	4.2.2*/4.2.3*	Hysteresis	4.2.x.200*	
		Delay	4.2.x.30*	
	Input	Active	4.2.4.1*	
	4.2.4*	Signal Outputs	4.2.4.2*	
		Output / Control	4.2.4.3*	
		Fault	4.2.4.4*	
		Delay	4.2.4.5*	
Logger	Log Interval	4.3.1*		
4.3*	Clear Logger	4.3.2*		

## 8.5. Installation (Main Menu 5)

<b>Sensors</b>	<b>Sensor parameters</b>	<i>Cell Constant</i>	5.1.1.1*	*Menu numbers
5.1*	5.1.1*	<i>Temp. Corr.</i>	5.1.1.2*	
		<i>Cable length</i>	5.1.1.3*	
	<b>Temp.Compensation</b>	<i>Comp.</i>	<i>none</i>	
	5.1.2*	5.1.2.1*	<i>Coefficient</i>	
			<i>non-linear DIN</i>	
	<b>Flow</b>	<i>Flow measurement</i>	<i>none</i>	
	5.1.3*	5.1.3.1*	<i>Q-Flow</i>	
			<i>deltaT</i>	
	<i>Conc.</i>	<i>none</i>		
	5.1.4*	<i>nitric acid</i>		
		<i>hydrochloric acid</i>		
		<i>sodium chloride</i>		
		<i>caustic soda</i>		
		<i>sulfuric acid</i>		
		<i>salinity</i>		
		<i>TDS as NaCl</i>		
		<i>TDS</i>		
<b>Signal Outputs</b>	<b>Signal Output 1/2</b>	<i>Parameter</i>	5.2.1.1/5.2.2.1*	
5.2*	5.2.1/5.2.2*	<i>Current Loop</i>	5.2.1.2/5.2.2.2*	
		<i>Function</i>	5.2.1.3/5.2.2.3*	
		<b>Scaling</b>	<i>Range Low</i>	5.2.x.40.10/11*
		5.2.x.40	<i>Range High</i>	5.2.x.40.20/21*
<b>Relay Contacts</b>	<b>Alarm Relay</b>	<b>Alarm Conductivity</b>	<i>Alarm High</i>	5.3.1.1.1.1*
5.3*	5.3.1*	5.3.1.1*	<i>Alarm Low</i>	5.3.1.1.1.25*
			<i>Hysteresis*</i>	5.3.1.1.1.35
			<i>Delay</i>	5.3.1.1.1.45*
		<b>Sample Flow</b>	<i>Flow Alarm</i>	5.3.1.2.1*
		5.3.1.2*	<i>Alarm High</i>	5.3.1.2.2
			<i>Alarm Low</i>	5.3.1.2.35
		<b>Sample Temp.</b>	<i>Alarm High</i>	5.3.1.3.1*
		5.3.1.3*	<i>Alarm Low</i>	5.3.1.3.25*
		<b>Case Temp.high</b>	<i>Case Temp. high</i>	5.3.1.4.1*
		5.3.1.4*	<i>Case Temp. low</i>	5.3.1.4.2*



Miscellaneous 5.4*	Relay 1/2 5.3.2/5.3.3*	Alarm Concentration	Alarm High	5.3.1.1.5.1*
		5.3.1.5*	Alarm Low	5.3.1.1.5.25*
			Hysteresis *	5.3.1.1.5.35
			Delay	5.3.1.1.5.45*
		Function	5.3.2.1/*	
	Input 5.3.4*	Parameter	5.3.2.20*	
		Setpoint	5.3.2.300 *	
		Hysteresis	5.3.2.400*	
		Delay	5.3.2.50*	
		Active	5.3.4.1*	
	Language 5.4.1*	Signal Outputs	5.3.4.2*	
		Output/Control	5.3.4.3*	
		Fault	5.3.4.4*	
		Delay	5.3.4.5*	
		Messages	5.4.4.1*	
Interface 5.5*	Set defaults 5.4.2*	Maintenance	5.4.4.2*	
		Operation	5.4.4.3*	
		Installation	5.4.4.4*	
		Sample ID	5.4.5*	
		Line break detection	5.4.6*	
	Password 5.4.4*	Protocol	5.5.1*	(only with RS485 interface)
		Device Address	5.5.21*	
		Baud Rate	5.5.31*	
		Parity	5.5.41*	

## 9. Program List and Explanations

### 1 Messages

#### 1.1 Pending Errors

- 1.1.5 Provides the list of active errors with their status (active, acknowledged). If an active error is acknowledged, the alarm relay is active again. Cleared errors are moved to the Message list.

#### 1.2 Message List

- 1.2.1 Shows the error history: Error code, date / time of issue and status (active, acknowledged, cleared). 65 errors are memorized. Then the oldest error is cleared to save the newest error (circular buffer).

### 2 Diagnostics

In diagnostics mode, the values can only be viewed, not modified.

#### 2.1 Identification

*Designation:* Designation of the instrument.

*Version:* Firmware of instrument (e.g. V6.20-09/16)

- 2.1.3 **Factory Test:** Test date of the Instrument, Motherboard and Frontend

- 2.1.4 **Operating Time:** Years / Days / Hours / Minutes / Seconds

#### 2.2 Sensors

##### 2.2.1 Cond. Sensor

- o *Current value* in  $\mu\text{S}$
- o *Raw value* in  $\mu\text{S}$
- o Cell Constant
- o Contamination

- 2.2.1.5 o *Cal. History:* In this menu the calibration values of the last calibrations are saved.
- o Number: Numbers the calibrations in descending order.
  - o Date, Time: Date and time of each calibration.
  - o Cell constant: Shows the cell constant of the sensor in use.

Max. 64 data records are memorized. One process calibration corresponds to one data record.

**2.2.2 Miscellaneous:**

- 2.2.2.1 *Case Temp*: Shows the current temperature in °C inside the transmitter.

**2.3 Sample**

- 2.3.1 *Sample ID*: Shows the identification assigned to a sample. This identification is defined by the user to identify the location of the sample.  
*Temperature*: Shows the current sample temperature in °C.  
*(Pt 1000)*: Shows the current sample temperature in Ohm.  
*Sample Flow*: If Q-Flow is chosen  
Shows the current sample flow in l/h  
*Raw Value*: shows the sample flow in Hz.  
*Sample Flow*: If deltaT is chosen  
Shows the current sample flow in l/h  
*deltaT 1*: Temperature measured at sample inlet of the deltaT sensor  
*deltaT 2*: Temperature measured at sample outlet of the deltaT sensor

**2.4 I/O State**

Shows current status of all in- and outputs.

- 2.4.1/2.4.2
- |                                   |                      |
|-----------------------------------|----------------------|
| <i>Alarm Relay</i> :              | Active or inactive   |
| <i>Relay 1 and 2</i> :            | Active or inactive   |
| <i>Input</i> :                    | Open or closed       |
| <i>Signal Output 1 and 2</i> :    | Actual current in mA |
| <i>Signal Output 3 (option)</i> : | Actual current in mA |

**2.5 Interface**

Only available if optional interface is installed.  
Review programmed communication settings.



## 3 Maintenance

### 3.1 Calibration

Follow the commands on the screen. Save the value with the [Enter] key.



### 3.2 Simulation

To simulate a value or a relay state, select the

- ♦ alarm relay,
- ♦ relay 1 or 2
- ♦ signal output 1 or 2

with the [  ] or [  ] key.

Press the [Enter] key.

Change the value or state of the selected item with the [  ] or [  ] key.

Press the [Enter] key.

⇒ *The value is simulated by the relay/signal output.*

*Alarm Relay:* Active or inactive

*Relay 1 and 2:* Active or inactive

*Signal Output 1 and 2:* Actual current in mA

*Signal Output 3 (option):* Actual current in mA

At the absence of any key activities, the instrument will switch back to normal mode after 20 min. If you quit the menu, all simulated values will be reset.

### 3.3 Set Time

Adjust date and time.

## 4 Operation

### 4.1 Sensors

- 4.1.1 *Filter Time Constant*: Used to damp noisy signals. The higher the filter time constant, the slower the system reacts to changes of the measured value.  
Range: 5–300 Sec
- 4.1.2 *Hold after Cal.*: Delay permitting the instrument to stabilize again after calibration. During calibration plus hold-time, the signal outputs are frozen (held on last valid value), alarm values, limits are not active.  
Range: 5–6'000 Sec

### 4.2 Relay Contacts

See [Relay Contacts](#), p. 31

### 4.3 Logger

The instrument is equipped with an internal logger. The logger data can be copied to a PC with an USB stick if option USB interface is installed.

The logger can save approx. 1500 data records. Records consist of: Date, time, alarms, measured value, measured value uncompensated, temperature, flow.

Range: 1 second to 1 hour

- 4.3.1 *Log Interval*: Select a convenient log interval. Consult the table below to estimate the max logging time. When the logging buffer is full, the oldest data record is erased to make room for the newest one (circular buffer).

Interval	1 s	5 s	1 min	5 min	10 min	30 min	1 h
Time	25 min	2 h	25 h	5 d	10 d	31 d	62 d

- 4.3.2 *Clear Logger*: If confirmed with **yes**, the complete logger data is deleted. A new data series is started.
- 4.3.3 If option USB interface is installed.  
*Eject USB Stick*: With this function all logger data are copied to the USB stick before the USB stick is deactivated.  
Only visible if the optional USB interface is installed.

## 5 Installation

### 5.1 Sensors

#### 5.1.1 Sensor parameters

- 5.1.1.1 *Cell Constant*: Enter the cell constant printed on the sensor label.
- 5.1.1.2 *Temp. Corr*: Enter the temperature correction printed on the sensor label.
- 5.1.1.3 *Cable length*: Enter the cable length. Set the cable length to 0.0 m if the sensor is installed in the flow cell on the AMI monitor.

#### 5.1.2 Temp. Compensation

- 5.1.2.1 *Comp.*: Available compensation models are:
  - ♦ none
  - ♦ Coefficient
  - ♦ non-linear DIN

#### 5.1.3 Flow

- 5.1.3.1 *Flow measurement*: Select the type of flow sensor if a flow sensor is installed.  
Possible flow sensors: None; Q-Flow; deltaT.
- 5.1.3.2 *Slope*: If flow measurement is set to deltaT.  
The slope value is used to adjust the flow measurement of the deltaT sensor if the ambient temperature is higher or lower than 20 °C.

#### 5.1.4 Conc.

The menu <Concentration> (Conc.) allows the additional measurement of a known substance in the sample. The concentration of the substance is calculated based on the conductivity of any of the following substances. The calculated value is displayed in %. As an exception, TDS is displayed in mg/l.

- ♦ none
- ♦ nitric acid
- ♦ hydrochloric acid
- ♦ sodium chloride
- ♦ caustic soda
- ♦ sulfuric acid
- ♦ salinity
- ♦ TDS as NaCl
- ♦ TDS

## 5.2 Signal Outputs

**5.2.1 and 5.2.2 Signal Output 1 and 2:** Assign process value, the current loop range and a function to each signal output.

**Note:** The navigation in the menu <Signal Output 1> and <Signal Output 2> is identical. For reason of simplicity only the menu numbers of Signal Output 1 are used in the following.

**5.2.1.1 Parameter:** Assign one of the process values to the signal output. Available values:

- ◆ Conductivity
- ◆ Temperature
- ◆ Sample flow
- ◆ Cond. uc (uncompensated)
- ◆ Concentration

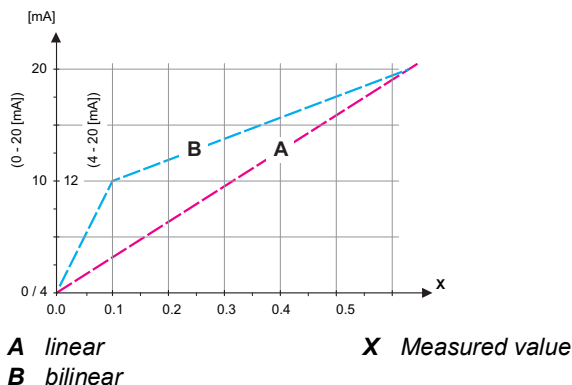
**5.2.1.2 Current Loop:** Select the current range of the signal output. Make sure the connected device works with the same current range. Available ranges: 0–20 mA or 4–20 mA

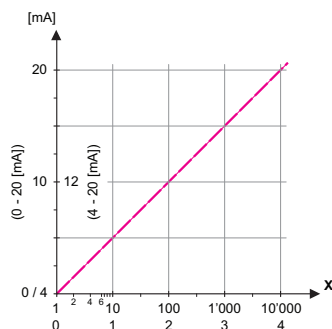
**5.2.1.3 Function:** Define if the signal output is used to transmit a process value or to drive a control unit. Available functions are:

- ◆ Linear, bilinear or logarithmic for process values.  
See [As process values, p. 60](#)
- ◆ Control upwards or control downwards for controllers.  
See [As control output, p. 62](#)

### As process values

The process value can be represented in 3 ways: linear, bilinear or logarithmic. See graphs below.





**X** Measured value (logarithmic)

**5.2.1.40 Scaling:** Enter beginning and end point (Range low & high) of the linear or logarithmic scale. In addition, the midpoint for the bilinear scale.

**Parameter Conductivity:**

5.2.1.40.10 Range low: 0  $\mu$ S–300 mS

5.2.1.40.20 Range high: 0  $\mu$ S–300 mS

**Parameter Temperature**

5.2.1.40.11 Range low: -25 to +270 °C

5.2.1.40.21 Range high: -25 to +270 °C

**Parameter Sample flow**

5.2.1.40.12 Range low: 0 –50 l/h

5.2.1.40.22 Range high: 0 –50 l/h

**Parameter Cond. uc:**

5.2.1.40.13 Range low: 0  $\mu$ S–300 mS

5.2.1.40.23 Range high: 0  $\mu$ S–300 mS

**Parameter Concentration**

5.2.1.40.14 Range low: 0–100% or 0.0 mg/l–20.00 g/l

5.2.1.40.24 Range high: 0–100% or 0.0 mg/l–20.00 g/l

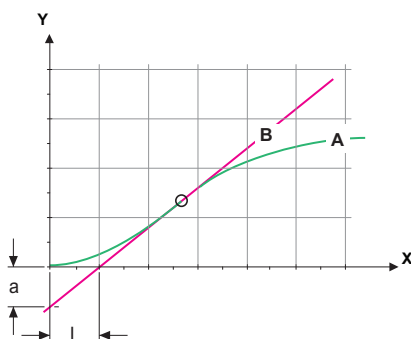
**As control output**

Signal outputs can be used for driving control units. We distinguish different kinds of controls:

- ♦ *P-controller*: The controller action is proportional to the deviation from the setpoint. The controller is characterized by the P-Band. In the steady-state, the setpoint will never be reached. The deviation is called steady-state error. Parameters: setpoint, P-Band
- ♦ *PI-controller*: The combination of a P-controller with an I-controller will minimize the steady-state error. If the reset time is set to zero, the I-controller is switched off. Parameters: setpoint, P-Band, reset time.
- ♦ *PD-controller*: The combination of a P-controller with a D-controller will minimize the response time to a fast change of the process value. If the derivative time is set to zero, the D-controller is switched off. Parameters: setpoint, P-Band, derivative time.
- ♦ *PID-controller*: The combination of a P-, an I - and a D-controller allows a proper control of the process. Parameters: setpoint, P-Band, reset time, derivative time.

Ziegler-Nichols method for the optimization of a PID controller:

**Parameters:** Setpoint, P-Band, Reset time, Derivative time



- |          |                                    |               |
|----------|------------------------------------|---------------|
| <b>A</b> | Response to maximum control output | $X_p = 1.2/a$ |
| <b>B</b> | Tangent on the inflection point    | $T_n = 2L$    |
| <b>X</b> | Time                               | $T_v = L/2$   |

The point of intersection of the tangent with the respective axis will result in the parameters a and L.

Consult the manual of the control unit for connecting and programming details. Choose control upwards or downwards.

### **Control upwards or downwards**

*Setpoint:* User-defined process value for the selected parameter.

*P-Band:* Range below (upwards control) or above (downwards control) the set-point, within the dosing intensity is reduced from 100% to 0% to reach the setpoint without overshooting.

- |                 |   |
|-----------------|---|
| <b>5.2.1.43</b> | <b>Control Parameters:</b> if Parameters = Conductivity   |
| 5.2.1.43.10     | Setpoint<br>Range: 0 µS–300 mS  |
| 5.2.1.43.20     | P-Band:<br>Range: 0 µS–300 mS   |
| <b>5.2.1.43</b> | <b>Control Parameters:</b> if Parameters = Temperature  |
| 5.2.1.43.11     | Setpoint<br>Range: -25 to +270 °C   |
| 5.2.1.43.21     | P-Band:<br>Range: -25 to +270 °C  |
| <b>5.2.1.43</b> | <b>Control Parameters:</b> if Parameters = Sample flow  |
| 5.2.1.43.12     | Setpoint<br>Range: 0 –50 l/h  |
| 5.2.1.43.22     | P-Band:<br>Range: 0 –50 l/h   |
| <b>5.2.1.43</b> | <b>Control Parameters:</b> if Parameters = Cond. uc.  |
| 5.2.1.43.13     | Setpoint<br>Range: 0 µS–300 mS  |
| 5.2.1.43.23     | P-Band:<br>Range: 0 µS–300 mS   |
| <b>5.2.1.43</b> | <b>Control Parameters:</b> if Parameters = Concentration  |
| 5.2.1.43.14     | Setpoint<br>Range: 0–100% or 0.0 mg/l–20.00 g/l   |
| 5.2.1.43.24     | P-Band:<br>Range: 0–100% or 0.0 mg/l–20.00 g/l  |
| 5.2.1.43.3      | <i>Reset time:</i> The reset time is the time till the step response of a single I-controller will reach the same value as it will be suddenly reached by a P-controller.<br>Range: 0–9'000 Sec           |
| 5.2.1.43.4      | <i>Derivative time:</i> The derivative time is the time till the ramp response of a single P-controller will reach the same value as it will be suddenly reached by a D-controller.<br>Range: 0–9'000 Sec |

- 5.2.1.43.5 *Control timeout:* If a controller action (dosing intensity) is constantly over 90% during a defined period of time and the process value does not come closer to the setpoint, the dosing process will be stopped for safety reasons.  
Range: 0–720 min

## 5.3 Relay Contacts

- 5.3.1 Alarm Relay:** The alarm relay is used as cumulative error indicator. Under normal operating conditions the contact is active.

The contact is inactive at:

- ♦ Power loss
- ♦ Detection of system faults like defective sensors or electronic parts
- ♦ High case temperature
- ♦ Process values out of programmed ranges.

Program alarm levels, hysteresis values and delay times for the following parameters:

- ♦ Alarm Conductivity
- ♦ Sample Flow
- ♦ Sample Temp.
- ♦ Case Temp.
- ♦ Alarm Concentration (visible if a Conc. parameter has been selected)

### 5.3.1.1 Alarm Conductivity

- 5.3.1.1.1 *Alarm High:* If the measured value rises above the alarm high value, the alarm relay is activated and E001, is displayed in the message list.

Range: 0  $\mu$ S–300 mS

- 5.3.1.1.25 *Alarm Low:* If the measured value falls below the alarm low value, the alarm relay is activated and E002 is displayed in the message list.

Range: 0  $\mu$ S–300 mS

- 5.3.1.1.35 *Hysteresis:* Within the hyst. range, the relay does not switch. This prevents damage of relays contacts when the measured value fluctuates around the alarm value.

Range. 0  $\mu$ S–300 mS



- 5.3.1.1.45 *Delay:* Duration, the activation of the alarm relay is retarded after the measuring value has risen above/fallen below the programmed alarm.  
Range: 0–28'800 Sec
- 5.3.1.2 Sample Flow:** Define at which sample flow an alarm should be issued.
- 5.3.1.2.1 *Flow Alarm:* Program if the alarm relay should be activated if there is a flow alarm. Choose between yes or no. The flow alarm will always be indicated in the display, pending error list, saved in the message list and the logger.  
Available values: Yes or no
- Note:** Sufficient flow is essential for a correct measurement.  
We recommend to program yes.*
- 5.3.1.2.2 *Alarm High:* If the measuring values rises above the programmed value E009 will be issued.  
Range: 9–20 l/h
- 5.3.1.2.35 *Alarm Low:* If the measuring values falls below the programmed value E010 will be issued.  
Range: 5–8 l/h
- 5.3.1.3 Sample Temp.**
- 5.3.1.3.1 *Alarm High:* If the measured value rises above the alarm high value, the alarm relay is activated and E007, is displayed in the message list.  
Range: 30–200 °C
- 5.3.1.3.25 *Alarm Low:* If the measured value falls below the alarm low value, the alarm relay is activated and E008 is displayed in the message list.  
Range: -10 to + 20 °C
- 5.3.1.4 Case Temp.**
- 5.3.1.4.1 *Case Temp. high:* Set the alarm high value for temperature of electronics housing. If the value rises above the programmed value E013 is issued.  
Range: 30–75 °C
- 5.3.1.4.2 *Case Temp. low:* Set the alarm low value for temperature of electronics housing. If the value falls below the programmed value E014 is issued.  
Range: -10 to +20 °C

**5.3.1.5 Alarm Concentration:** Visible if a Conc. parameter has been selected. TDS is displayed in mg/l, all other parameters are displayed in %.

5.3.1.5.1 *Alarm High:* If the measured value rises above the alarm high value, the alarm relay is activated and E003 is displayed in the message list.

Range: 0.00%–99.90%

5.3.1.5.25 *Alarm Low:* If the measured value falls below the alarm low value, the alarm relay is activated and E004 is displayed in the message list.

Range: 0.00%–99.90%

5.3.1.5.35 *Hysteresis:* Within the hyst. range, the relay does not switch. This prevents damage of relay contacts when the measured value fluctuates around the alarm value.

Range: 0.00%–99.90%

5.3.1.5.45 *Delay:* Duration, the activation of the alarm relay is retarded after the measuring value has risen above or fallen below the programmed alarm.

Range: 0–28'800 Sec

**5.3.2 and 5.3.3 Relay 1 and 2:** The contacts can be set as normally open or normally closed with a jumper. See [Relay Contacts 1 and 2, p. 32](#). The function of relay contacts 1 or 2 are defined by the user.

**Note:** *The navigation in the menu <Relay 1> and <Relay 2> is identical. For reason of simplicity only the menu numbers of Relay 1 are used in the following.*

- 1 First select the functions as:
  - Limit upper/lower,
  - Control upwards/downwards,
  - Timer
  - Fieldbus
- 2 Then enter the necessary data depending on the selected function.

**5.3.2.1 Function = Limit upper/lower:**

When the relays are used as upper or lower limit switches, program the following:

5.3.2.20 *Parameter:* select a process value

5.3.2.300 *Setpoint:* If the measured value rises above respectively falls below the set-point, the relay is activated.

Parameter	Range
Conductivity	0 $\mu$ S–300 mS
Temperature	-25 to +270 °C
Sample flow	0–50 l/h
Cond. uc	0 $\mu$ S–300 mS

5.3.2.400 *Hysteresis:* within the hysteresis range, the relay does not switch. This prevents damage of relay contacts when the measured value fluctuates around the alarm value.

Parameter	Range
Conductivity	0 $\mu$ S–300 mS
Temperature	-25 to +270 °C
Sample flow	0–50 l/h
Cond. uc	0 $\mu$ S–300 mS

5.3.2.50 *Delay:* Duration, the activation of the alarm relay is retarded after the measuring value has risen above/fallen below the programmed alarm.  
 Range. 0–600 Sec

**5.3.2.1 Function = Control upwards/downwards:**

The relays may be used to drive control units such as solenoid valves, membrane dosing pumps or motor valves. When driving a motor valve both relays are needed, relay 1 to open and relay 2 to close the valve.

5.3.2.22 *Parameter:* Choose on of the following process values.

- ♦ Conductivity)
- ♦ Temperature
- ♦ Sample Flow
- ♦ Cond. uc

**5.3.2.32 Settings:** Choose the respective actuator:

- ♦ Time proportional
- ♦ Frequency
- ♦ Motor valve

5.3.2.32.1 Actuator = Time proportional

Examples of metering devices that are driven time proportional are solenoid valves, peristaltic pumps.

Dosing is controlled by the operating time.

5.3.2.32.20 *Cycle time:* duration of one control cycle (on/off change).

Range: 0–600 sec.

5.3.2.32.30 *Response time:* Minimal time the metering device needs to react.

Range: 0–240 sec.

**5.3.2.32.4 Control Parameters**

Range for each Parameter same as [5.2.1.43, p. 63](#)

5.3.2.32.1 Actuator = Frequency

Examples of metering devices that are pulse frequency driven are the classic membrane pumps with a potential free triggering input. Dosing is controlled by the repetition speed of dosing shots.

5.3.2.32.21 *Pulse frequency:* Max. pulses per minute the device is able to respond to.

Range: 20–300/min.

**5.3.2.32.31 Control Parameters**

Range for each Parameter same as [5.2.1.43, p. 63](#)

5.3.2.32.1 Actuator = Motor valve

Dosing is controlled by the position of a motor driven mixing valve.

5.3.2.32.22 *Run time:* Time needed to open a completely closed valve

Range: 5–300 Sec.

5.3.2.32.32 *Neutral zone:* Minimal response time in % of the runtime. If the requested dosing output is smaller than the response time, no change will take place.

Range: 1–20 %

**5.3.2.32.4 Control Parameters**

Range for each Parameter same as [5.2.1.43, p. 63](#)

5.3.2.1 **Function = Timer:**

The relay will be activated repetitively depending on the programmed time scheme.

5.3.2.24 **Mode:** Operating mode (interval, daily, weekly)

5.3.2.24 **Interval**

5.3.2.340 **Interval:** The interval can be programmed within a range of 1–1'440 min.

5.3.2.44 **Run Time:** Enter the time the relay stays active.  
 Range: 5–32'400 sec.

5.3.2.54 **Delay:** during run time plus the delay time the signal and control outputs are held in the operating mode programmed below.  
 Range: 0–6'000 Sec.

5.3.2.6 **Signal Outputs:** Select operating mode of the signal output:

**Cont.:** Signal outputs continue to issue the measured value.

**Hold:** Signal outputs hold the last valid measured value.  
 Measurement is interrupted. Errors, except fatal errors, are not issued.

**Off:** Signal outputs are switched off (set to 0 or 4 mA).  
 Errors, except fatal errors, are not issued.

5.3.2.7 **Output/Control:** Select operating mode of the controller output:

**Cont.:** Controller continues normally.

**Hold:** Controller continues based on the last valid value.

**Off:** Controller is switched off.

5.3.2.24 **daily**

The relay contact can be activated daily, at any time of a day.

5.3.2.341 **Start time:** to set the start time proceed as follows:

- 1 Press [Enter], to set the hours.
- 2 Set the hour with the [▲] or [▼] keys.
- 3 Press [Enter], to set the minutes.
- 4 Set the minutes with the [▲] or [▼] keys.
- 5 Press [Enter], to set the seconds.
- 6 Set the seconds with the [▲] or [▼] keys.

Range: 00:00:00–23:59:59

- 5.3.2.44 *Run Time*: see Interval
- 5.3.2.54 *Delay*: see Interval
- 5.3.2.6 *Signal Outputs*: see Interval
- 5.3.2.7 *Output/Control*: see Interval

#### 5.3.2.24 *weekly*

The relay contact can be activated at one or several days, of a week.  
 The daily starting time is valid for all days.

### 5.3.2.342 **Calendar:**

- 5.3.2.342.1 *Start time*: The programmed start time is valid for each of the programmed days. To set the start time see [5.3.2.341](#), p. 69.

Range: 00:00:00–23:59:59

- 5.3.2.342.2 *Monday*: Possible settings, on or off to

- 5.3.2.342.8 *Sunday*: Possible settings, on or off

- 5.3.2.44 *Run Time*: see Interval
- 5.3.2.54 *Delay*: see Interval
- 5.3.2.6 *Signal Outputs*: see Interval
- 5.3.2.7 *Output/Control*: see Interval

#### 5.3.2.1 **Function = Fieldbus:**

The relay will be switched via the Profibus input. No further parameters are needed.

- 5.3.4 **Input:**** The functions of the relays and signal outputs can be defined depending on the position of the input contact, i.e. no function, closed or open.

- 5.3.4.1 *Active*: Define when the input should be active:

- No:* Input is never active.
- When closed* Input is active if the input relay is closed
- When open:* Input is active if the input relay is open

- 5.3.4.2 *Signal Outputs:* Select the operation mode of the signal outputs when the relay is active:
- Cont.:* Signal outputs continue to issue the measured value.
- Hold:* Signal outputs issue the last valid measured value. Measurement is interrupted. Errors, except fatal errors, are not issued.
- Off:* Set to 0 or 4 mA respectively. Errors, except fatal errors, are not issued.
- 5.3.4.3 *Output/Control:* (relay or signal output):
- Cont.:* Controller continues normally.
- Hold:* Controller continues on the last valid value.
- Off:* Controller is switched off.
- 5.3.4.4 *Fault:*
- No:* No message is issued in pending error list and the alarm relay does not close when input is active. Message E024 is stored in the message list.
- Yes:* Message E024 is issued and stored in the message list. The Alarm relay closes when input is active.
- 5.3.4.5 *Delay:* Time which the instrument waits, after the input is deactivated, before returning to normal operation.  
 Range: 0–6'000 Sec

## 5.4 Miscellaneous

- 5.4.1 *Language:* Set the desired language.

Language
German
English
French
Spanish

5.4.2     *Set defaults:* Reset the instrument to factory default values in three different ways:

Set defaults
no
Calibration
In parts
Completely

- ♦ **Calibration:** Sets calibration values back to default. All other values are kept in memory.
- ♦ **In parts:** Communication parameters are kept in memory. All other values are set back to default values.
- ♦ **Completely:** Sets back all values including communication parameters.

5.4.3     *Load Firmware:* Firmware updates should be done by instructed service personnel only.

Load Firmware
no
yes

**5.4.4     Password:** Select a password different from 0000 to prevent unauthorized access to the following menus:

5.4.4.1    Messages

5.4.4.2    Maintenance

5.4.4.3    Operation

5.4.4.4    Installation.

Each menu may be protected by a *different* password.  
If you forgot the passwords, contact the closest SWAN representative.

5.4.5     *Sample ID:* Identify the process value with any meaning full text, such as KKS number.

5.4.6     *Line Break Detection:* Define if message E028 should be issued in case of a line break on signal output 1 or 2.  
Choose between <Yes> or <No>.



## 5.5 Interface

Select one of the following communication protocols. Depending on your selection, different parameters must be defined.

### 5.5.1 *Protocol:* **Profibus**

- 5.5.20 Device address: Range: 0–126
- 5.5.30 ID-Nr.: Range: Analyzer; Manufacturer; Multivariable
- 5.5.40 Local operation: Range: Enabled, Disabled

### 5.5.1 *Protocol:* **Modbus RTU**

- 5.5.21 Device address: Range: 0–126
- 5.5.31 Baud Rate: Range: 1 200–115 200 Baud
- 5.5.41 Parity: Range: none, even, odd

### 5.5.1 *Protocol:* **USB-Stick:**

Only visible if an USB interface is installed. No further settings are possible.

### 5.5.1 *Protocol:* **HART**

- Device address: Range: 0–63



## 10. Default Values

### Operation:

Sensors:	Filter Time Const.: .....	10 s
	Hold after Cal.: .....	300 s
Relay Contacts	Alarm Relay .....	same as in Installation
	Relay 1/2 .....	same as in Installation
	Input .....	same as in Installation
Logger:	Logger Interval: .....	30 min
	Clear Logger: .....	no

### Installation:

Sensors	Sensor Parameters; Cell Constant .....	0.4000 cm <sup>-1</sup>
	Sensor Parameters; Temp. corr. ....	0.00 °C
	Sensor Parameters; Cable length .....	0.0 m
	Temp. Compensation; Comp. ....	none
	Flow; Flow measurement .....	none
Signal Output 1	Conc.: .....	none
	Parameter: .....	Conductivity
	Current loop: .....	4–20 mA
	Function: .....	linear
	Scaling: Range low: .....	0.000 µS
Signal Output 2	Scaling: Range high: .....	100 mS
	Parameter: .....	Temperature
	Current loop: .....	4–20 mA
	Function: .....	linear
	Scaling: Range low: .....	0.0 °C
Alarm Relay:	Scaling: Range high: .....	50.0 °C
	Alarm Conductivity:	
	Alarm high: .....	300 mS
	Alarm low: .....	0.00 µS
	Hysteresis: .....	1.00 mS
	Delay: .....	5 s
	Sample Flow (if Flow measurement = yes):	
	Flow Alarm .....	yes
	Alarm high: .....	50.0 l/h
	Alarm low: .....	5.0 l/h
Sample Temp:	Alarm High: .....	120 °C
	Alarm Low: .....	0 °C

	Case Temp. high: .....	65 °C
	Case Temp. low: .....	0 °C
Relay 1 and 2	Function: .....	limit upper
	Parameter: .....	Conductivity
	Setpoint: .....	100 mS
	Hysteresis: .....	1 mS
	Delay: .....	30 s
	<b>If Function = Control upw. or dnw:</b>	
	Parameter: .....	Conductivity
	Settings: Actuator: .....	Frequency
	Settings: Pulse Frequency: .....	120/min
	Settings: Control Parameters: Setpoint: .....	100 mS
	Settings: Control Parameters: P-band: .....	1 mS
	Settings: Control Parameters: Reset time: .....	0 s
	Settings: Control Parameters: Derivative Time: .....	0 s
	Settings: Control Parameters: Control Timeout: .....	0 min
	Settings: Actuator: .....	Time proportional
	Cycle time: .....	60 s
	Response time: .....	10 s
	Settings: Actuator: .....	Motor valve
	Run time: .....	60 s
	Neutral zone: .....	5%
	<b>If Function = Timer:</b>	
	Mode: .....	Interval
	Interval: .....	1 min
	Mode: .....	daily
	Start time: .....	00.00.00
	Mode: .....	weekly
	Calendar; Start time: .....	00.00.00
	Calendar; Monday to Sunday: .....	Off
	Run time: .....	10 s
	Delay: .....	5 s
	Signal output: .....	cont
	Output/Control: .....	cont
Input:	Active .....	when closed
	Signal Outputs .....	hold
	Output/Control .....	off
	Fault .....	no
	Delay .....	10 s

Miscellaneous    Language:.....English  
                      Set default: ..... no  
                      Load firmware:..... no  
                      Password:.....for all modes 0000  
                      Sample ID:.....- - - - -  
                      Line break detection ..... no

## 11. Index

### **A**

Actuators . . . . .	33
Alarm Relay . . . . .	9, 31
Application Range . . . . .	9

### **C**

Cable thicknesses . . . . .	27
Calendar . . . . .	70
Calibration solution . . . . .	44
Cell constant . . . . .	10, 37
Changing values . . . . .	41
Checklist . . . . .	20
Cleaning	
Sensor . . . . .	43
Concentration . . . . .	59

### **D**

Default Values . . . . .	74
--------------------------	----

### **E**

Error List . . . . .	46
----------------------	----

### **F**

Fluidics . . . . .	10
--------------------	----

### **H**

HART . . . . .	36
----------------	----

### **I**

Inductive load . . . . .	33
Input . . . . .	10, 31
Instrument Overview . . . . .	14
Interface . . . . .	10
HART . . . . .	36
Modbus . . . . .	35
Profibus . . . . .	35

USB . . . . .	36
---------------	----

### **M**

Measuring principle . . . . .	10
Measuring Range . . . . .	12
Modbus . . . . .	35
Mounting . . . . .	21

### **O**

On-site requirements . . . . .	12
--------------------------------	----

### **P**

Power Supply . . . . .	12, 30
Profibus . . . . .	36
Programming . . . . .	37

### **R**

Relay Contacts 1 and 2 . . . . .	32
Relays . . . . .	9
Resistive load . . . . .	33

### **S**

Safety Features . . . . .	10
Sample flow, establish . . . . .	37
Sample requirements . . . . .	12
Sensor parameters . . . . .	59
Set Time . . . . .	57
Setup . . . . .	37
Signal Output . . . . .	60
Current loop . . . . .	60
Signal Outputs . . . . .	9, 34
Simulation . . . . .	57
Software . . . . .	40
Specifications	
Swansensor deltaT . . . . .	19

**T**

Technical Data . . . . .	14
Temperature compensation . . . . .	10
Terminals . . . . .	29, 31–32, 35

**U**

USB Interface . . . . .	36
-------------------------	----

## 12. Notes

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