

AMU Solicon4

Version 6.20 and higher



Operator's Manual



Customer Support

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AMU Solicon4–Operator’s Manual

This document describes the main steps for instrument setup, operation and maintenance.

1. Safety Instructions

General	<p>The instructions included in this section explain the potential risks associated with instrument operation and provide important safety practices designed to minimize these risks.</p> <p>If you carefully follow the information contained in this section, you can protect yourself from hazards and create a safer work environment.</p> <p>More safety instructions are given throughout this manual, at the respective locations where observation is most important.</p> <p>Strictly follow all safety instructions in this publication.</p>
Target audience	<p>Operator: Qualified person who uses the equipment for its intended purpose.</p> <p>Instrument operation requires thorough knowledge of applications, instrument functions and software program as well as all applicable safety rules and regulations.</p>
OM Location	<p>The AMI Operator’s Manual shall be kept in proximity of the instrument.</p>
Qualification, Training	<p>To be qualified for instrument installation and operation, you must:</p> <ul style="list-style-type: none">♦ read and understand the instructions in this manual as well as the Material Safety Data Sheets.♦ know the relevant safety rules and regulations.

1.1. Warning Notices

The symbols used for safety-related notices have the following significance:



DANGER

Your life or physical wellbeing are in serious danger if such warnings are ignored.

- ♦ Follow the prevention instructions carefully.



WARNING

Severe injuries or damage to the equipment can occur if such warnings are ignored.

- ♦ Follow the prevention instructions carefully.



CAUTION

Damage to the equipment, minor injury, malfunctions or incorrect process can be the consequence if such warnings are ignored.

- ♦ Follow the prevention instructions carefully.

Mandatory Signs

The importance of the mandatory signs in this manual.



Safety goggles



Safety gloves

Warning Signs The importance of the warning signs in this manual.



Electrical shock hazard



Corrosive



Harmful to health



Flammable



Warning general



Attention general

1.2. General Safety Regulations

Legal Requirements

The user is responsible for proper system operation. All precautions must be followed to ensure safe operation of the instrument.

Spare Parts and Disposables

Use only official SWAN spare parts and disposables. If other parts are used during the normal warranty period, the manufacturer's warranty is voided.

Modifications

Modifications and instrument upgrades shall only be carried out by an authorized Service Technician. SWAN will not accept responsibility for any claim resulting from unauthorized modification or alteration.

WARNING



Risk of Electrical Shock

If proper operation is no longer possible, the instrument must be disconnected from all power lines, and measures must be taken to prevent inadvertent operation.

- ♦ To prevent from electrical shock, always make sure that the ground wire is connected.
- ♦ Service shall be performed by authorized personnel only.
- ♦ Whenever electronic service is required, disconnect instrument power and power of devices connected to.
 - relay 1,
 - relay 2,
 - alarm relay



WARNING

For safe instrument installation and operation you must read and understand the instructions in this manual.



WARNING

Only SWAN trained and authorized personnel shall perform the tasks described in this document.

2. Product Description

2.1. Description of the System

This instrument is applicable for the measurement of the specific conductivity in surface water, potable water and cooling water.

Application Range	Conductivity is a parameter for the total quantity of ions present in the solution. It can be used for the controlling of: <ul style="list-style-type: none">♦ the condition of waters♦ water purification♦ water hardness♦ completeness of ion analysis
Signal Outputs	Two signal outputs programmable for measured values (freely scalable, linear, bilinear, log) or as continuous control output (control parameters programmable). Current loop: 0/4–20 mA Maximal burden: 510 Ohm
Relays	Two potential-free contacts programmable as limit switches for measuring values, controllers or timer for system cleaning with automatic hold function. Maximum load: 100 mA/50 V
Alarm Relay	One potential free contact. Summary alarm indication for programmable alarm values and Instrument faults. Available in two configurations: <ul style="list-style-type: none">♦ Normally open*: Closed during normal operation, open in case of error or power loss.♦ Normally closed: Open during normal operation, closed in case of error or power loss *Standard configuration. To order the version with normally closed alarm relay, contact your dealer in advance. Maximum load: 100 mA / 50 V
Input	For potential-free contact to freeze the signal outputs or to interrupt control in automated installations (<i>hold</i> function or <i>remote-off</i>).
Communication interface	<ul style="list-style-type: none">♦ RS232 for logger download with HyperTerminal♦ RS485 with Fieldbus protocol Modbus or Profibus DP (optional)

Safety Features No data loss after power failure. All data is saved in non-volatile memory.
Over voltage protection of in- and outputs.
Galvanic separation of measuring inputs and signal outputs.

Temperature compensation The mobility of ions in water increase with higher temperature which enlarges the conductivity. Therefore, the temperature is measured simultaneously by an integrated Pt1000 temperature sensor and the conductivity is compensated to 25 °C.

Measuring principle When a voltage is set between two electrodes in an electrolyte solution, the result is an electric field which exerts force on the charged ions: the positively charged cations move towards the negative electrode (cathode) and the negatively charged anions towards the positive electrode (anode). The ions, by way of capture or release of electrons at the electrodes, are discharged and so a current I flows through this cycle and the Ohms law $V = I \times R$ applies. From the total resistance R of the current loop, only the resistance of the electrolyte solution, respectively its conductivity $1/R$, is of interest.

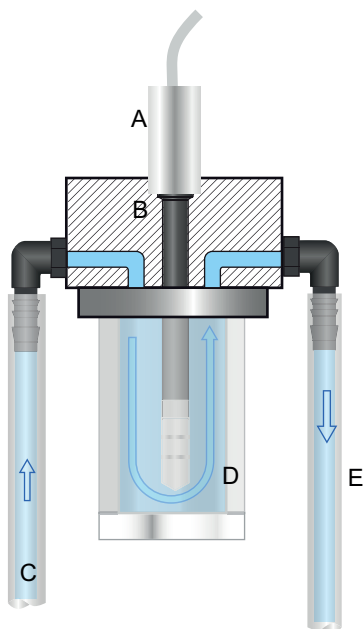
The cell constant of the sensor is determined by the manufacturer and is printed on the sensor label. If the cell constant has been programmed in the transmitter, the instrument measures correctly. No calibration must be done, the sensor is factory calibrated.

Fluidics The flow cell M-Flow PG consists of the flow cell block [B] and the calibration vessel [D].

The conductivity sensor [A] is fixed in the flow cell block [B] with a threaded sleeve.

The sample enters at the sample inlet [F]. It flows through the flow cell block into the calibration vessel [D], where the conductivity is measured.

The sample leaves the calibration vessel via flow cell block through the sample outlet [E] and flows into the drain [G].



A Conductivity sensor
B Flow cell block
C Sample inlet

D Calibration vessel
E Sample outlet

2.2. Single Components

2.2.1 AMU Solicon4 Transmitter

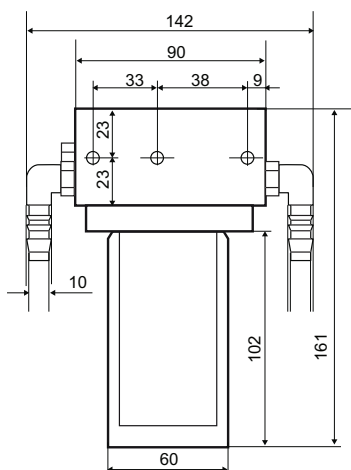


General	Electronics housing:	Noryl® resin
	Protection degree:	IP54 (front)
	Ambient temperature:	-10 to +50 °C
	Humidity:	10–90% rel., non condensing
	Display:	backlit LCD, 75 x 45 mm
	Dimensions:	96 x 96 x 120 mm (DIN 43700)
Power supply	Weight:	0.45 kg
	Voltage:	100–240 VAC (±10%)
		50/60 Hz (±5%)
		or 24 VDC (±15%)
Conductivity sensor type	Power consumption:	max. 8 VA
	4-electrode sensor	

Measuring range	Range	Resolution
	0.05–9.99 $\mu\text{S/cm}$	0.01 $\mu\text{S/cm}$
	10.0–99.9 $\mu\text{S/cm}$	0.1 $\mu\text{S/cm}$
	100–999 $\mu\text{S/cm}$	1 $\mu\text{S/cm}$
	1.00–9.99 mS/cm	0.01 mS/cm
	10.0–29.9 mS/cm	0.1 mS/cm
	30–100 mS/cm	1 mS/cm
	Automatic range switching. Values for a cell constant of 0.4000 cm^{-1} (Swansensors Shurecon P and Shurecon S).	
Sensor cell constant	0.005–1.000 cm^{-1}	
Temperature compensation	<ul style="list-style-type: none"> ♦ none ♦ coefficient ♦ non-linear DIN 	
Temperature measurement	Pt1000 type sensor (DIN class A) Measuring range: -30 to +250 °C Resolution: 0.1 °C	
Sample flow measurement	with digital SWAN sample flow sensor	

2.2.2 Flow Cell M-Flow PG and M-Flow G1

- ♦ Flow cell M-Flow PG, made of PVC and acrylic glass with one 13.5 mm sensor opening for Swansensor Shurecon P.
- or
- ♦ Flow cell M-Flow G1, made of PVC and acrylic glass with one G 1" sensor opening for Swansensor Shurecon S.



Sample connections

Inlet: G 1/4" thread
Outlet: G 1/4" thread

Each equipped with an elbow hose nozzle for 10 mm tube.

Sample conditions

Only valid for the flow cell without sensor.

Flow rate: 4 to 15 l/h
Temperature: up to 50 °C
Inlet pressure: up to 1 bar @ 25 °C
Sample outlet: Pressure-free outlet
Particle size: below 0.5 mm

No strong acids and bases.

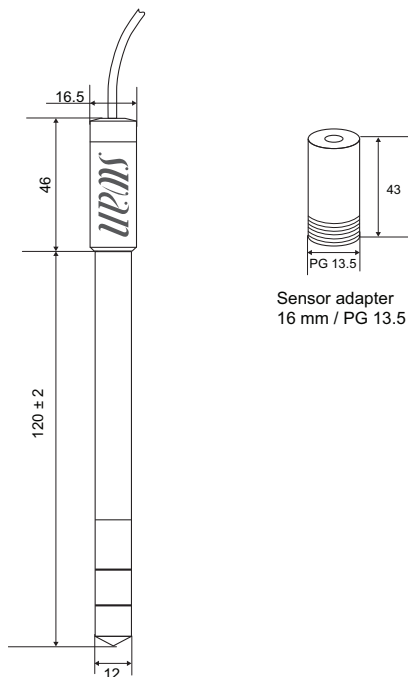
No organic solvents.

Dimensions

Width: 90 to 142 mm
Front-to-back: 105 mm
Height: 161 mm
Panel mounting: 3 screws M5

2.2.3 Swansensor Shurecon P

Sensor with integrated cable for the measurement of the specific conductivity. Four electrode design with platinum electrodes and built-in Pt1000 temperature sensor.



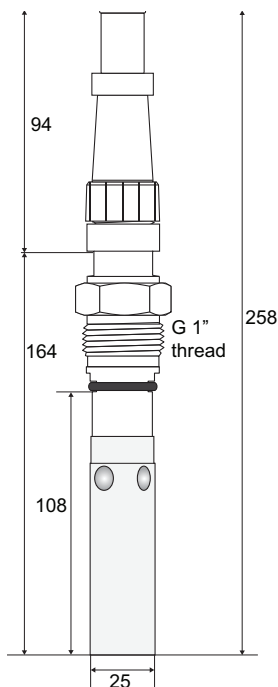
Sensor adapter
16 mm / PG 13.5

Specifications

Measuring range	0.1 $\mu\text{S}/\text{cm}$ to 100 mS/cm
Accuracy:	$\pm 1.5\%$ or $\pm 0.2 \mu\text{S}/\text{cm}$ whichever is greater
Temperature sensor:	Pt 1000
Operating conditions:	$> 50^\circ\text{C}$ Max. temperature short-time 90°C Max. pressure 10 bar at 25°C .
Electrical connection:	Sensor with integrated cable
Process connection:	PG 13.5 mm

2.2.4 Swansensor Shurecon S

Sensor for the measurement of the specific conductivity. Four electrode design with integrated Pt 1000 temperature sensor. Screw connector with cable must be ordered separately.



Specifications

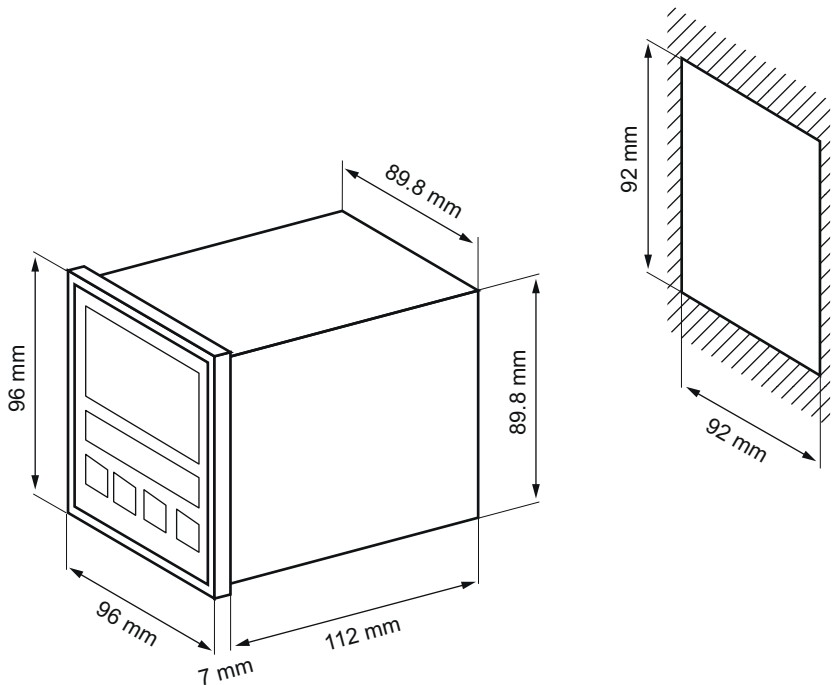
Measuring range	0.1 $\mu\text{S}/\text{cm}$ to 100 mS/cm
Accuracy:	$\pm 1\%$ or $\pm 0.2 \mu\text{S}/\text{cm}$ whichever is greater
Temperature sensor:	Pt 1000
Operating conditions:	Max. temperature: 120 °C at 6.5 bar
	Max. pressure: 12 bar at 20 °C
	Sterilizable at: 120 °C / 5 bar / 30 min
Electrical connection:	Plug M16 male (IP 67)
Process connection:	G 1" thread
Space around sensor tip:	20 mm

3. Installation

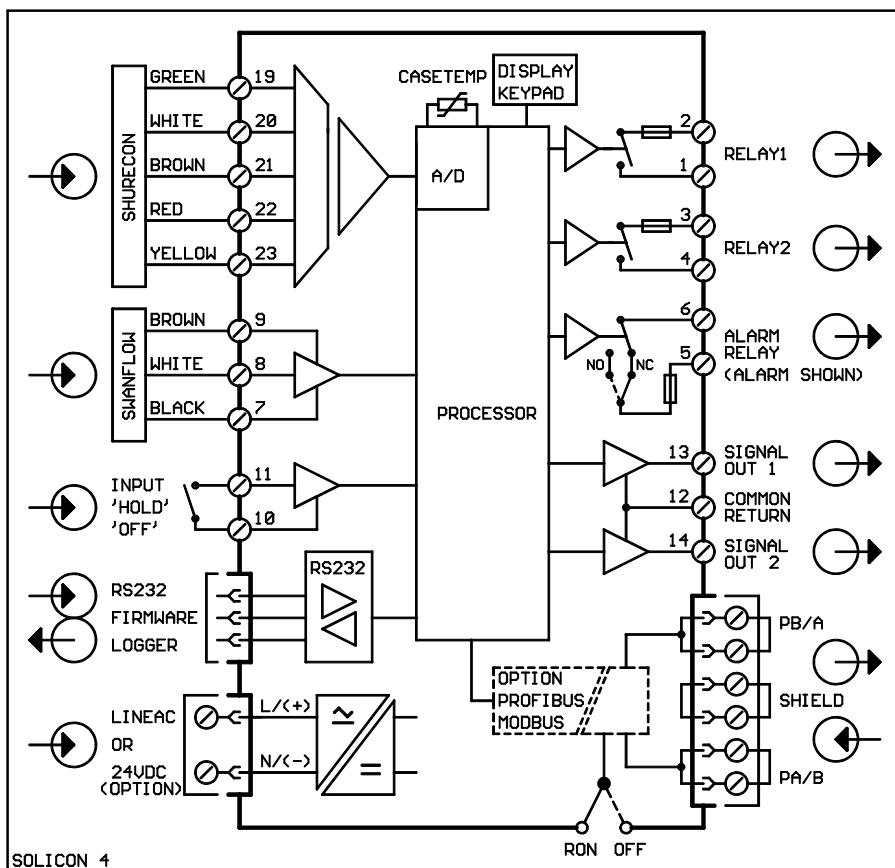
3.1. Installation Checklist

Check	Instrument's specification must conform to your power ratings. Do not turn on power until instructed to do so.
Installation	The transmitter is intended for panel mounting. The dimensions are shown under Dimensions of the AMU Transmitter, p. 16.
Electrical connections	Connect all external devices, see Electrical Connections, p. 17. Connect the power cord, but do not switch on power until all external devices are connected.
Power-up	Open sample flow and wait until flow cell is completely filled. Switch on power. Adjust sample flow.
Instrument set-up	Program all sensor parameters see Programming, p. 23. Program the required temperature compensation. Program all parameters for external devices (interface, recorders, etc.). Program all parameters for instrument operation (limits, alarms).
Run-in period	Let the instrument run continuously for 1 h.
Calibration	Perform a calibration if necessary, see Calibration, p. 30.

3.2. Dimensions of the AMU Transmitter



3.3. Electrical Connections

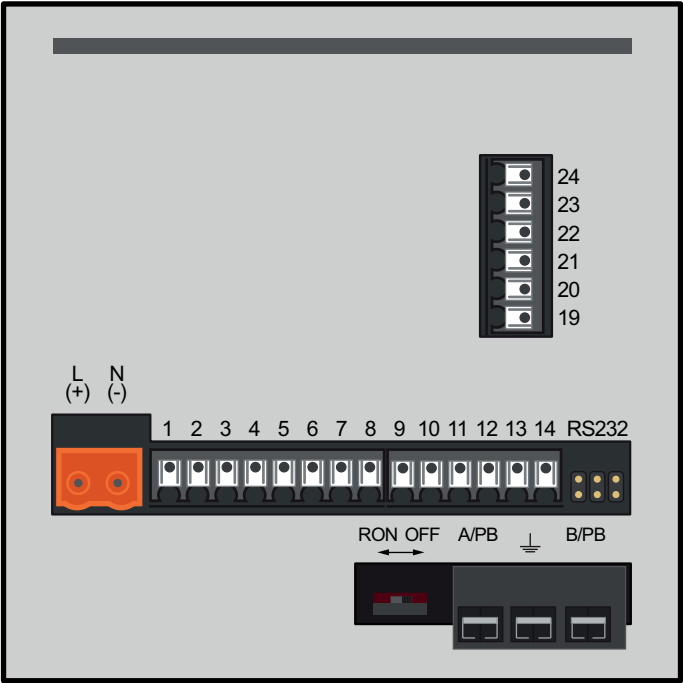


CAUTION



Use only the terminals shown in this diagram, and only for the mentioned purpose. Use of any other terminals will cause short circuits with possible corresponding consequences to material and personnel.

Rear view
of AMU
Transmitter

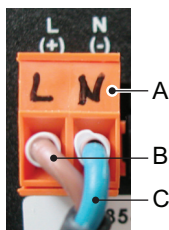


3.4. Power supply



CAUTION

Do not apply power to the transmitter until all electrical connections have been made.



A Power supply connector

B Phase conductor

C Neutral conductor

Installation requirements

The installation must meet the following requirements:

- ♦ Mains cable according to standards IEC 60227 or IEC 60245; flammability rating FV1
- ♦ Mains equipped with an external switch or circuit-breaker
 - near the instrument
 - easily accessible to the operator
 - marked as interrupter for AMU Solicon4

3.5. Sensor

Connect the sensor to the AMU transmitter according to the connection diagram, see [Electrical Connections, p. 17](#).

For sensor settings, see [Programming, p. 23](#).

3.6. Flow Meter

Connect the flow meter (if any) to the AMU transmitter according to the connection diagram, see [Electrical Connections, p. 17](#).

3.7. Input

NOTICE: Use only potential-free (dry) contacts.

Terminals 10/11

For programming see [Program List and Explanations, p. 40](#).

3.8. Relay Contacts

3.8.1 Alarm Relay

NOTICE: Max. load 100 mA/50 V

Alarm output for system errors. Error codes see [Error List, p. 32](#).

	Terminals	Description
NC ^{a)} Normally Closed	5/6	Active (opened) during normal operation. Inactive (closed) on error and loss of power.
NO ^{a)} Normally Open	5/6	Active (closed) during normal operation. Inactive (opened) on error and loss of power.

a) As defined when ordering

3.8.2 Relay 1 and 2

NOTICE: Max. load 100 mA/50 V

Relay 1: Terminals 1/2

Relay 2: Terminals 3/4

For programming see [Program List and Explanations, p. 40](#), Menu Installation

3.9. Signal Output 1 and 2 (current outputs)

NOTICE: Max. burden 510 Ω

If signals are sent to two different receivers, use signal isolator (loop isolator).

Signal output 1: Terminals 13 (+) and 12 (-)

Signal output 2: Terminals 14 (+) and 12 (-)

For programming see [Program List and Explanations, p. 40](#), Menu Installation

3.10. Interfaces

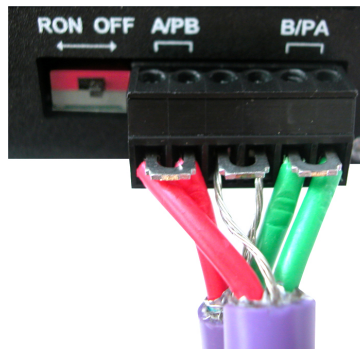
3.10.1 RS232 Interface

The RS232 interface is located on the back of the AMU transmitter.



The RS232 interface is used for logger download and firmware upload.

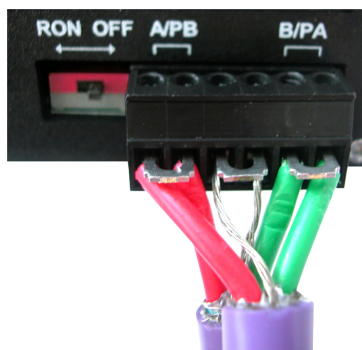
3.10.2 Profibus (optional)



To connect several instruments by means of a network or to configure a PROFIBUS DP connection, consult the PROFIBUS manual. Use appropriate network cable.

NOTICE: The switch must be ON if only one instrument is installed, or on the last instrument in the bus

3.10.3 Modbus (optional)



To connect several instruments by means of a network consult the MODBUS manual. Use appropriate network cable.

NOTICE: *The switch must be ON if only one instrument is installed, or on the last instrument in the bus*

4. Instrument Setup

4.1. Establish Sample Flow

- 1 Open sample flow tap.
- 2 Wait until the flow cell is completely filled.
- 3 Switch on power.

4.2. Programming

Programming

The sensor characteristics are printed on the label of the sensor. Program all sensor parameters in Menu 5.1.1.1, <Installation> <Sensors> <Sensor parameters>:

SW-xx-xx-xx	ZK = 0.0417	Cell constant
SWAN AG		Temperature correction

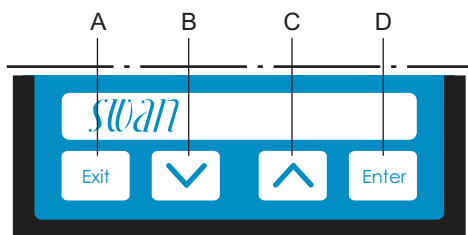
Enter the:

- ♦ Cell constant [cm^{-1}]
- ♦ Temperature correction [$^{\circ}\text{C}$]
- ♦ Cable length

Program all parameters for external devices (interface, recorders, etc.). Program all parameters for instrument operation (limits, alarms). See [Program List and Explanations, S. 40](#).

5. Operation

5.1. Keys

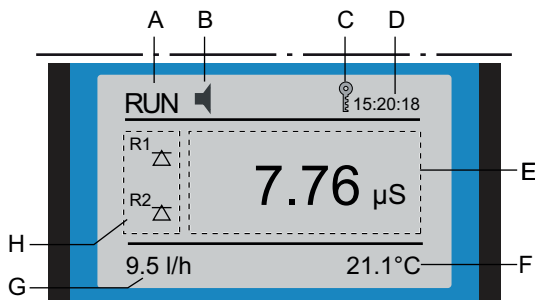




- A** to exit a menu or command (rejecting any changes)
to move back to the previous menu level
- B** to move DOWN in a menu list and to decrease digits
- C** to move UP in a menu list and to increase digits
- D** to open a selected sub-menu
to accept an entry

Program Access, Exit













5.2. Display



- | | | |
|----------|---|---|
| A | RUN | normal operation |
| | HOLD | input closed or cal delay: Instrument on hold (shows status of signal outputs). |
| | OFF | input closed: control/limit is interrupted (shows status of signal outputs). |
| B | ERROR |  Error  Fatal Error |
| C | Keys locked, transmitter control via Profibus | |
| D | Time | |
| E | Process value | |
| F | Sample temperature | |
| G | Sample flow | |
| H | Relay status | |

Relay status, symbols

- | | |
|---|--|
|  | upper limit not yet reached |
|  | upper limit reached |
|  | lower limit not yet reached |
|  | lower limit reached |
|  | control upw./downw. no action |
|  | control upw./downw. active, dark bar indicates control intensity |
|  | motor valve closed |
|  | motor valve: open, dark bar indicates approx. position |
|  | timer |
|  | timer: timing active (hand rotating) |

5.3. Software Structure

Main Menu	1
Messages	▶
Diagnostics	▶
Maintenance	▶
Operation	▶
Installation	▶

Messages	1.1
Pending Errors	▶
Message List	▶

Menu **Messages 1**

Reveals pending errors as well as an event history (time and state of events that have occurred at an earlier point of time).
It contains user relevant data.

Diagnostics	2.1
Identification	▶
Sensors	▶
Sample	▶
I/O State	▶
Interface	▶

Menu **Diagnostics 2**

Provides user relevant instrument and sample data.

Maintenance	3.1
Calibration	▶
Process Cal.	▶
Simulation	▶
Set Time	23.09.06 16:30:00

Menu **Maintenance 3**

For instrument calibration, relay and signal output simulation, and to set the instrument time.
It is used by the service personnel.

Operation	4.1
Sensors	▶
Relay Contacts	▶
Logger	▶

Menu **Operation 4**

User relevant parameters that might need to be modified during daily routine. Normally password protected and used by the process operator.
Subset of menu 5 - Installation, but process-related.

Installation	5.1
Sensors	▶
Signal Outputs	▶
Relay Contacts	▶
Miscellaneous	▶
Interface	▶

Menu **Installation 5**

For initial instrument set up by SWAN authorized person, to set all instrument parameters. Can be protected by means of password.

5.4. Changing Parameters and values

Changing parameters

The following example shows how to change the logger interval:

Logger 4.4.1
Log interval 30 min
Clear logger no

- 1 Select the parameter you want to change.
- 2 Press [Enter]

Logger 4.1.3
Log interval Interval.
Clear log 5 min
10 min
30 min
1 Hour

- 3 Press [] or [] key to highlight the required parameter.
- 4 Press [Enter] to confirm the selection or [Exit] to keep the previous parameter).

Logger 4.1.3
Log interval 10 min
Clear logger no

⇒ The selected parameter is highlighted but not saved yet.

- 5 Press [Exit].

Logger 4.1.3
Log interval Save ?
Clear log Yes
No

⇒ Yes is highlighted.

- 6 Press [Enter] to save the new parameter.

⇒ The system reboots, the new parameter is set.

Changing values

Alarm Conductivity 5.3.1.1.1
Alarm High 300 mS
Alarm Low 0.00 µS
Hysteresis 1.00 µS
Delay 5 Sec

- 1 Select the value you want to change.

- 2 Press [Enter].

- 3 Set required value with [] or [] key.

Alarm Conductivity 5.3.1.1.1
Alarm High 120 mS
Alarm Low 0.00 µS
Hysteresis 1.00 µS
Delay 5 Sec

- 4 Press [Enter] to confirm the new value.

- 5 Press [Exit].

⇒ Yes is highlighted.

- 6 Press [Enter] to save the new value.

6. Maintenance



WARNING

Stop operation before maintenance.

- ♦ Stop sample flow.
- ♦ Shut off power of the instrument.

6.1. Maintenance Schedule

Preventive maintenance frequency depends on water quality, on the application, and on national regulations.

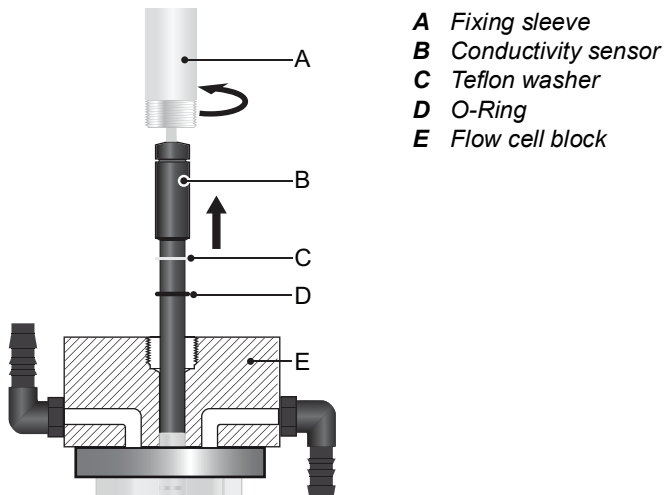
Monthly	<ul style="list-style-type: none"> ♦ Check sample flow.
If required	<ul style="list-style-type: none"> ♦ Clean conductivity sensor ♦ Perform a calibration

6.2. Stop of Operation for Maintenance

Stop sample flow.

Shut off power of the instrument.

6.3. Maintenance of the Sensor



6.3.1 Remove the Sensor from the Flow Cell

To remove the sensor from the flow cell proceed as follows:

- 1 Unscrew and remove the fixing sleeve [A].
- 2 Pull the conductivity sensor [B] out of the flow cell block [E].

Cleaning

If the sensor is contaminated, take a small brush and clean it with water and detergents.

In case of heavy contamination with oil or grease, use ethanol to clean it. Take a soft tissue and clean the tip of the sensor cautiously.

After each cleaning, the sensor must be rinsed with clean water.

6.3.2 Install the Sensor into the Flow Cell

- 1 Make sure that the washer [C] and the O-ring [D] are in correct position.
- 2 Push the sensor through the flow cell block [E] into the flow cell.
- 3 Tighten the fixing sleeve [A] to fix the sensor.

6.4. Calibration

Since the sensor is very reliable a calibration is usually not necessary. A calibration is recommended if:

- ♦ the cell constant is not known
- ♦ the sensor is contaminated
- ♦ the maintenance measurement shows a discrepancy.

Reagent for calibration

Calibration solution 1.413 mS/cm (25 °C) 1000 ml. Prepare according to DIN 38404 / ISO 7888: 1985 / EN 27888.

- 1 Stop the sample flow.
- 2 Navigate to menu <Maintenance> / <Calibration>.
- 3 Press [Enter] and follow the dialog on the Display.
- 4 Remove the sensor from the flow cell.
- 5 Clean the sensor carefully and rinse it with clean water, see [Maintenance of the Sensor, p. 29](#).
- 6 Use a beaker and fill it with one liter calibration solution.
⇒ *The beaker's diameter must be large enough to allow a distance of at least 3 cm between the sensor and the edge of the beaker.*
- 7 Put the sensor into the beaker filled with calibration solution.

Calibration	3.1.5
Clean the sensor and place it in standard solution	

[Enter] to continue	

Calibration	3.1.5
Sensor must have a min. distance of 3 cm from the beakers edge	

[Enter] to continue	

Calibration	3.1.1
Standard solution	1.41 mS
Current Value	10.07 µS
Cell constant	0.406 cm ⁻¹

Progress	<div style="width: 50%;"></div>

- 8 Wait at least 5 minutes to permit temperature equilibration between sensor and calibration solution.
- 9 Start the calibration procedure.

10 Press [Enter], to save the values if the calibration was successful.

11 Install the sensor into the flow cell.

6.5. Longer Stop of Operation

- 1 Stop sample flow.
- 2 Shut off power of the instrument.
- 3 Remove the sensor from the flow cell and dry it with a soft tissue.
- 4 Empty and dry the flow cell.

7. Error List

Error

Non-fatal Error. Indicates an alarm if a programmed value is exceeded.

Such Errors are marked **E0xx**.

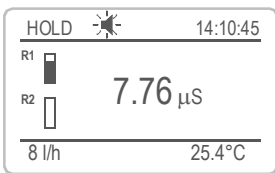
Fatal Error (blinking symbol)

Control of dosing devices is interrupted.

The indicated measured values are possibly incorrect.

Fatal Errors are divided in the following two categories:

- Errors which disappear if correct measuring conditions are recovered (i.e. Sample Flow low).
Such Errors are marked **E0xx**
- Errors which indicate a hardware failure of the instrument.
Such Errors are marked **E0xx**

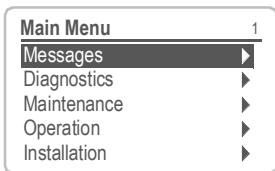


Error or fatal Error

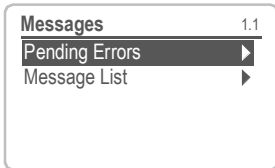
Error not yet acknowledged.

Check **Pending Errors 1.1.5 *** and take corrective action.

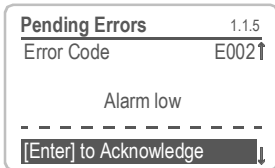
Press [ENTER].



Navigate to menu Messages.
Press [ENTER].



Navigate to menu Pending Errors.
Press [ENTER].



Press [ENTER] to acknowledge the Pending Errors. The Error is reset and saved in the Message List.

Error	Description	Corrective action
E001	Cond. Alarm high	<ul style="list-style-type: none"> – check process – check programmed value, see 5.3.1.1, p. 49
E002	Cond. Alarm low	<ul style="list-style-type: none"> – check process – check programmed value, see 5.3.1.1, p. 49
E003	Conc. Alarm high	<ul style="list-style-type: none"> – check process – check programmed value, see 5.3.1.5, p. 50
E004	Conc. Alarm low	<ul style="list-style-type: none"> – check process – check programmed value, see 5.3.1.5, p. 50
E007	Sample Temp. high	<ul style="list-style-type: none"> – check process – check programmed value, see 5.3.1.3, p. 50
E008	Sample Temp. low	<ul style="list-style-type: none"> – check process – check programmed value, see 5.3.1.3, p. 50
E009	Sample Flow high	<ul style="list-style-type: none"> – check sample inlet pressure – check programmed value, see 5.3.1.2.2, p. 49
E010	Sample Flow low	<ul style="list-style-type: none"> – check sample inlet pressure – Check flow regulating valve – check programmed value, see 5.3.1.2.35, p. 49
E011	Temp. shorted	<ul style="list-style-type: none"> – Check wiring of sensor
E012	Temp. disconnected	<ul style="list-style-type: none"> – Check wiring of sensor
E013	Case Temp. high	<ul style="list-style-type: none"> – check case/environment temperature – check programmed value, see 5.3.1.4.1, p. 50
E014	Case Temp. low	<ul style="list-style-type: none"> – check case/environment temperature – check programmed value, see 5.3.1.4.2, p. 50

Error	Description	Corrective action
E017	Control time-out	– Check control device or programming in Installation, Relay contact, Relay 1/2 5.3.2 and 5.3.3 , p. 51
E018	Temp. out of Table	– Check sample temperature
E019	Conc. out of Table	–
E024	Input active	– See If Fault Yes is programmed in Menu see 5.3.4 , p. 55
E026	IC LM75	– call service
E030	EEProm Frontend	– call service
E031	Cal. Recout	– call service
E032	Wrong Frontend	– call service
E033	Power-on	– none, normal status
E034	Power-down	– none, normal status

8. Program Overview

For explanations about each parameter of the menus see [Program List and Explanations, p. 40](#).

- ♦ Menu 1 **Messages** informs about pending errors and maintenance tasks and shows the error history. Password protection possible. No settings can be modified.
- ♦ Menu 2 **Diagnostics** is always accessible for everybody. No password protection. No settings can be modified.
- ♦ Menu 3 **Maintenance** is for service: Calibration, simulation of outputs and set time/date. Please protect with password.
- ♦ Menu 4 **Operation** is for the user, allowing to set limits, alarm values, etc. The presetting is done in the menu Installation (only for the System engineer). Please protect with password.
- ♦ Menu 5 **Installation**: Defining assignment of all inputs and outputs, measuring parameters, interface, passwords, etc. Menu for the system engineer. Password strongly recommended.

8.1. Messages (Main Menu 1)

Pending Errors

1.1*

Pending Errors

1.1.5*

* Menu numbers

Message List

1.2*

Number

1.2.1*

Date, Time

8.2. Diagnostics (Main Menu 2)

Identification	Designation	AMU Solicon4	* Menu numbers
2.1*	Version	V6.20-09/16	
	Factory Test	Instrument	2.1.3.1*
	2.1.3*	Motherboard	
		Front End	
	Operating Time	Years / Days / Hours / Minutes / Seconds	2.1.4.1*
	2.1.4*		
Sensors	Cond. Sensor	Current value	
2.2*	2.2.1*	Raw value	
		Cell constant	
		Contamination	
	Cal. History	Number,	2.2.1.5.1*
	2.2.1.5*	Date, Time	
		Cell Constant	
	Miscellaneous	Case Temp.	2.2.2.1*
	2.2.2*		
Sample	Sample ID	2.3.1*	
2.3*	Temperature	°C	
	(Pt1000)	Ohm	
	Sample Flow	l/h	
	Raw value	Hz	
I/O State	Alarm Relay	2.4.1*	
2.4*	Relay 1 and 2	2.4.2*	
	Input		
	Signal Output 1 and 2		
Interface	Protocol	2.5.1*	
2.5*	Baud rate		

8.3. Maintenance (Main Menu 3)

Calibration	Follow instructions	3.1.5*	*Menu numbers
3.1*			
Simulation	Alarm Relay	3.3.1*	
3.2*	Relay 1	3.3.2*	
	Relay 2	3.3.3*	
	Signal Output 1	3.3.4*	
	Signal Output 2	3.3.5*	
Set Time	(Date), (Time)		
3.3*			

8.4. Operation (Main Menu 4)

Sensors	Filter Time Const.	4.1.1*	* Menu number
4.1*	Hold after Cal	4.1.2*	
Relay Contacts	Alarm Relay	Alarm Conductivity	Alarm High 4.2.1.1.1*
4.2*	4.2.1*	4.2.1.1*	Alarm Low 4.2.1.1.25*
			Hysteresis 4.2.1.1.35*
			Delay 4.2.1.1.45*
	If concentration	Alarm Concentration	Alarm High 4.2.1.2.1*
	is chosen	4.2.1.2*	Alarm Low 4.2.1.2.25*
			Hysteresis 4.2.1.2.35*
			Delay 4.2.1.2.45*
	Relay 1/2	Setpoint	4.2.x.100*
	4.2.2*/4.2.3*	Hysteresis	4.2.x.200*
		Delay	4.2.x.30*
	Input	Active	4.2.4.1*
	4.2.4*	Signal Outputs	4.2.4.2*
		Output / Control	4.2.4.3*
		Fault	4.2.4.4*
		Delay	4.2.4.5*
Logger	Log Interval	4.3.1*	
4.3*	Clear Logger	4.3.2*	

S

8.5. Installation (Main Menu 5)

Sensors	Sensor parameters			*Menu numbers
5.1*	5.1.1*	Cell Constant	5.1.1.1*	
		Temp. Corr.	5.1.1.2*	
		Cable length	5.1.1.3*	
	Temp.Compensation	Comp.	none	
	5.1.2*	5.1.2.1*	Coefficient	
			non-linear DIN	
	Flow	Flow measurement	none	
	5.1.3*	5.1.3.1*	Q-Flow	
			delta T	
	Conc.	none		
	5.1.4*	nitric acid		
		hydrochloric acid		
		sodium chloride		
		caustic soda		
		sulfuric acid		
		salinity		
		TDS as NaCl		
		TDS		
Signal Outputs	Signal Output 1/2	Parameter	5.2.1.1/5.2.2.1*	
5.2*	5.2.1/5.2.2*	Current Loop	5.2.1.2/5.2.2.2*	
		Function	5.2.1.3/5.2.2.3*	
		Scaling	Range Low	5.2.x.40.10/11*
		5.2.x.40	Range High	5.2.x.40.20/21*
Relay Contacts	Alarm Relay	Alarm Conductivity	Alarm High	5.3.1.1.1.1*
5.3*	5.3.1*	5.3.1.1*	Alarm Low	5.3.1.1.1.25*
			Hysteresis *	5.3.1.1.1.35
			Delay	5.3.1.1.1.45*
		Sample Flow	Flow Alarm	5.3.1.2.1*
		5.3.1.2*	Alarm High	5.3.1.2.2
			Alarm Low	5.3.1.2.35
		Sample Temp.	Alarm High	5.3.1.3.1*
		5.3.1.3*	Alarm Low	5.3.1.3.25*
		Case Temp.high	Case Temp. high	5.3.1.4.1*
		5.3.1.4*	Case Temp. low	5.3.1.4.2*

		Alarm Concentration	<i>Alarm High</i>	5.3.1.1.5.1*
		5.3.1.5*	<i>Alarm Low</i>	5.3.1.1.5.25*
			<i>Hysteresis</i> *	5.3.1.1.5.35*
			<i>Delay</i>	5.3.1.1.5.45*
	Relay 1/2	<i>Function</i>	5.3.2.1/*	
	5.3.2/5.3.3*	<i>Parameter</i>	5.3.2.20 *	
		<i>Setpoint</i>	5.3.2.300 *	
		<i>Hysteresis</i>	5.3.2.400*	
		<i>Delay</i>	5.3.2.50*	
	Input	<i>Active</i>	5.3.4.1*	
	5.3.4*	<i>Signal Outputs</i>	5.3.4.2*	
		<i>Output/Control</i>	5.3.4.3*	
		<i>Fault</i>	5.3.4.4*	
		<i>Delay</i>	5.3.4.5*	
Miscellaneous	<i>Language</i>	5.4.1*		
5.4*	<i>Set defaults</i>	5.4.2*		
	<i>Load Firmware</i>	5.4.3*		
	Password	<i>Messages</i>	5.4.4.1*	
	5.4.4*	<i>Maintenance</i>	5.4.4.2*	
		<i>Operation</i>	5.4.4.3*	
		<i>Installation</i>	5.4.4.4*	
	<i>Sample ID</i>	5.4.5*		
Interface	<i>Protocol</i>	5.5.1*		
5.5*	<i>Device Address</i>	5.5.21*		
	<i>Baud Rate</i>	5.5.31*		
	<i>Parity</i>	5.5.41*		

* Menu numbers

9. Program List and Explanations

1 Messages

1.1 Pending Errors

- 1.1.5 Provides the list of active errors with their status (active, acknowledged). If an active error is acknowledged, the alarm relay is active again. Cleared errors are moved to the Message list.

1.2 Message List

- 1.2.1 Shows the error history: Error code, date / time of issue and status (active, acknowledged, cleared). 65 errors are memorized. Then the oldest error is cleared to save the newest error (circular buffer).

2 Diagnostics

In diagnostics mode, the values can only be viewed, not modified.

2.1 Identification

Designation: Designation of the instrument.

Version: Firmware of instrument (e.g. V6.20-09/16)

- 2.1.3 **Factory Test:** Test date of the Instrument, Motherboard and Frontend

- 2.1.4 **Operating Time:** Years / Days / Hours / Minutes / Seconds

2.2 Sensors

2.2.1 Cond. Sensor

- o *Current value* in μS
- o *Raw value* in μS
- o Cell Constant
- o Contamination

- 2.2.1.5
- o *Cal. History:* In this menu the calibration values of the last calibrations are saved.
 - o *Number:* Numbers the calibrations in descending order.
 - o *Date, Time:* Date and time of each calibration.
 - o *Cell constant:* Shows the cell constant of the sensor in use.

Max. 64 data records are memorized. One process calibration corresponds to one data record.

2.2.2 Miscellaneous:

- 2.2.2.1 *Case Temp*: Shows the current temperature in °C inside the transmitter.

2.3 Sample

- 2.3.1 *Sample ID*: Shows the identification assigned to a sample. This identification is defined by the user to identify the location of the sample.

Temperature: Shows the current sample temperature in °C.

(Pt 1000): Shows the current sample temperature in Ohm.

Sample Flow: Shows the current sample flow in l/h

Raw Value: shows the sample flow in Hz.

2.4 I/O State

Shows current status of all in- and outputs.

2.4.1/2.4.2

Alarm Relay: Active or inactive

Relay 1 and 2: Active or inactive

Input: Open or closed

Signal Output 1 and 2: Actual current in mA

2.5 Interface

Only available if optional interface is installed.

Review programmed communication settings.

3 Maintenance

3.1 Calibration

Follow the commands on the screen. Save the value with the [Enter] key.



3.2 Simulation

To simulate a value or a relay state, select the

- ♦ alarm relay,
- ♦ relay 1 or 2
- ♦ signal output 1 or 2

with the [] or [] key.

Press the [Enter] key.

Change the value or state of the selected item with the [] or [] key.

Press the [Enter] key.

⇒ *The value is simulated by the relay/signal output.*

Alarm Relay: Active or inactive

Relay 1 and 2: Active or inactive

Signal Output 1 and 2: Actual current in mA

At the absence of any key activities, the instrument will switch back to normal mode after 20 min. If you quit the menu, all simulated values will be reset.

3.3 Set Time

Adjust date and time.

4 Operation

4.1 Sensors

4.1.1 *Filter Time Constant:* Used to damp noisy signals. The higher the filter time constant, the slower the system reacts to changes of the measured value.

Range: 5–300 Sec

4.1.2 *Hold after Cal.:* Delay permitting the instrument to stabilize again after calibration. During calibration plus hold-time, the signal outputs are frozen (held on last valid value), alarm values, limits are not active.

Range: 5–6'000 Sec

4.2 Relay Contacts

See [Relay Contacts, p. 20](#)

4.3 Logger

The instrument is equipped with an internal logger. The logger data can be downloaded to a PC using the built-in RS232 interface.

The logger can save approx. 1500 data records. Records consist of: Date, time, alarms, measured value, measured value uncompensated, temperature, flow.

Range: 1 second to 1 hour

4.3.1 *Log Interval:* Select a convenient log interval. Consult the table below to estimate the max logging time. When the logging buffer is

full, the oldest data record is erased to make room for the newest one (circular buffer).

Interval	1 s	5 s	1 min	5 min	10 min	30 min	1 h
Time	25 min	2 h	25 h	5 d	10 d	31 d	62 d

- 4.3.2 *Clear Logger*: If confirmed with **yes**, the complete logger data is deleted. A new data series is started.

5 Installation

5.1 Sensors

5.1.1 Sensor parameters

- 5.1.1.1 *Cell Constant*: Enter the cell constant printed on the sensor label.
- 5.1.1.2 *Temp. Corr.*: Enter the temperature correction printed on the sensor label.
- 5.1.1.3 *Cable length*: Enter the cable length.

5.1.2 Temp. Compensation

- 5.1.2.1 *Comp.*: Available compensation models are:
- ◆ none
 - ◆ Coefficient
 - ◆ non-linear DIN

5.1.3 Flow

- 5.1.3.1 *Flow measurement*: Select the type of flow sensor if a flow sensor is installed.
- Possible flow sensors: None; Q-Flow.

5.1.4 Conc.

The menu <Concentration> (Conc.) allows the additional measurement of a known substance in the sample. The concentration of the substance is calculated based on the conductivity of any of the following substances. The calculated value is displayed in %. As an exception, TDS is displayed in mg/l.

- ♦ none
- ♦ nitric acid
- ♦ hydrochloric acid
- ♦ sodium chloride
- ♦ caustic soda
- ♦ sulfuric acid
- ♦ salinity
- ♦ TDS as NaCl
- ♦ TDS

5.2 Signal Outputs

5.2.1 and 5.2.2 Signal Output 1 and 2: Assign process value, the current loop range and a function to each signal output.

NOTICE: The navigation in the menu <Signal Output 1> and <Signal Output 2> is identical. For reason of simplicity only the menu numbers of Signal Output 1 are used in the following.

5.2.1.1 Parameter: Assign one of the process values to the signal output.

Available values:

- ♦ Conductivity
- ♦ Temperature
- ♦ Sample flow
- ♦ Cond. uc (uncompensated)
- ♦ Concentration

5.2.1.2 Current Loop: Select the current range of the signal output. Make sure the connected device works with the same current range.

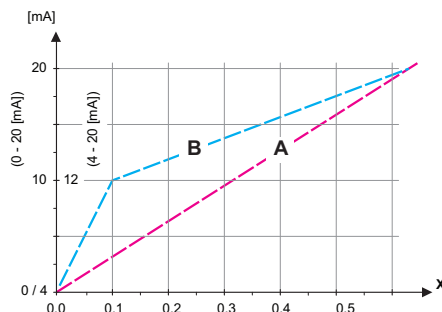
Available ranges: 0–20 mA or 4–20 mA

5.2.1.3 Function: Define if the signal output is used to transmit a process value or to drive a control unit. Available functions are:

- ♦ Linear, bilinear or logarithmic for process values.
See [As process values, p. 45](#)
- ♦ Control upwards or control downwards for controllers.
See [As control output, p. 46](#)

As process values

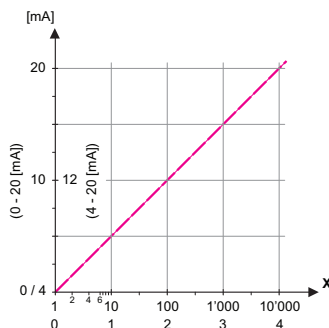
The process value can be represented in 3 ways: linear, bilinear or logarithmic. See graphs below.



A linear

B bilinear

X Measured value



X Measured value (logarithmic)

5.2.1.40

Scaling: Enter beginning and end point (Range low & high) of the linear or logarithmic scale. In addition, the midpoint for the bilinear scale.

Parameter Conductivity:

5.2.1.40.10 Range low: 0 μ S–300 mS

5.2.1.40.20 Range high: 0 μ S–300 mS

Parameter Temperature

5.2.1.40.11 Range low: -25 to +270 °C

5.2.1.40.21 Range high: -25 to +270 °C

Parameter Sample flow

5.2.1.40.12 *Range low:* 0 –50 l/h

5.2.1.40.22 *Range high:* 0 –50 l/h

Parameter Cond. uc:

5.2.1.40.13 *Range low:* 0 μ S–300 mS

5.2.1.40.23 *Range high:* 0 μ S–300 mS

Parameter Concentration

5.2.1.40.14 *Range low:* 0–100 % or 0.0 mg/l–20.00 g/l

5.2.1.40.24 *Range high:* 0–100 % or 0.0 mg/l–20.00 g/l

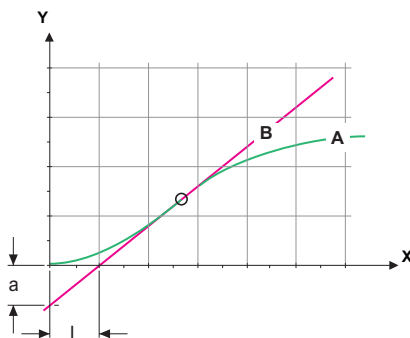
As control output

Signal outputs can be used for driving control units. We distinguish different kinds of controls:

- ♦ *P-controller:* The controller action is proportional to the deviation from the setpoint. The controller is characterized by the P-Band. In the steady-state, the setpoint will never be reached. The deviation is called steady-state error.
Parameters: setpoint, P-Band
- ♦ *PI-controller:* The combination of a P-controller with an I-controller will minimize the steady-state error. If the reset time is set to zero, the I-controller is switched off.
Parameters: setpoint, P-Band, reset time.
- ♦ *PD-controller:* The combination of a P-controller with a D-controller will minimize the response time to a fast change of the process value. If the derivative time is set to zero, the D-controller is switched off.
Parameters: setpoint, P-Band, derivative time.
- ♦ *PID-controller:* The combination of a P-, an I - and a D-controller allows a proper control of the process.
Parameters: setpoint, P-Band, reset time, derivative time.

Ziegler-Nichols method for the optimization of a PID controller:

Parameters: Setpoint, P-Band, Reset time, Derivative time



- A** Response to maximum control output $Xp = 1.2/a$
B Tangent on the inflection point $Tn = 2L$
X Time $Tv = L/2$

The point of intersection of the tangent with the respective axis will result in the parameters a and L.

Consult the manual of the control unit for connecting and programming details. Choose control upwards or downwards.

Control upwards or downwards

Setpoint: User-defined process value for the selected parameter.

P-Band: Range below (upwards control) or above (downwards control) the set-point, within the dosing intensity is reduced from 100% to 0% to reach the setpoint without overshooting.

5.2.1.43

Control Parameters: if Parameters = Conductivity

5.2.1.43.10

Setpoint

Range: 0 μ S–300 mS

5.2.1.43.20

P-Band:

Range: 0 μ S–300 mS

5.2.1.43

Control Parameters: if Parameters = Temperature

5.2.1.43.11

Setpoint

Range: -25 to +270 °C

5.2.1.43.21

P-Band:

Range: -25 to +270 °C

- 5.2.1.43 Control Parameters:** if Parameters = Sample flow
- 5.2.1.43.12 Setpoint
Range: 0 –50 l/h
- 5.2.1.43.22 P-Band:
Range: 0 –50 l/h
- 5.2.1.43 Control Parameters:** if Parameters = Cond. uc.
- 5.2.1.43.13 Setpoint
Range: 0 μ S–300 mS
- 5.2.1.43.23 P-Band:
Range: 0 μ S–300 mS
- 5.2.1.43 Control Parameters:** if Parameters = Concentration
- 5.2.1.43.14 Setpoint
Range: 0–100% or 0.0 mg/l–20.00 g/l
- 5.2.1.43.24 P-Band:
Range: 0–100% or 0.0 mg/l–20.00 g/l
- 5.2.1.43.3 **Reset time:** The reset time is the time till the step response of a single I-controller will reach the same value as it will be suddenly reached by a P-controller.
Range: 0–9'000 Sec
- 5.2.1.43.4 **Derivative time:** The derivative time is the time till the ramp response of a single P-controller will reach the same value as it will be suddenly reached by a D-controller.
Range: 0–9'000 Sec
- 5.2.1.43.5 **Control timeout:** If a controller action (dosing intensity) is constantly over 90% during a defined period of time and the process value does not come closer to the setpoint, the dosing process will be stopped for safety reasons.
Range: 0–720 min

5.3 Relay Contacts

- 5.3.1 Alarm Relay:** The alarm relay is used as cumulative error indicator. Under normal operating conditions the contact is active.
The contact is inactive at:
- ♦ Power loss
 - ♦ Detection of system faults like defective sensors or electronic parts
 - ♦ High case temperature
 - ♦ Process values out of programmed ranges.

Program alarm levels, hysteresis values and delay times for the following parameters:

- ♦ Alarm Conductivity
- ♦ Sample Flow
- ♦ Sample Temp.
- ♦ Case Temp.
- ♦ Alarm Concentration (visible if a Conc. parameter has been selected)

5.3.1.1 Alarm Conductivity

5.3.1.1.1 *Alarm High:* If the measured value rises above the alarm high value, the alarm relay is activated and E001, is displayed in the message list.

Range: 0 μ S–300 mS

5.3.1.1.25 *Alarm Low:* If the measured value falls below the alarm low value, the alarm relay is activated and E002 is displayed in the message list.

Range: 0 μ S–300 mS

5.3.1.1.35 *Hysteresis:* Within the hyst. range, the relay does not switch. This prevents damage of relays contacts when the measured value fluctuates around the alarm value.

Range: 0 μ S–300 mS

5.3.1.1.45 *Delay:* Duration, the activation of the alarm relay is retarded after the measuring value has risen above/fallen below the programmed alarm.

Range: 0–28'800 Sec

5.3.1.2 **Sample Flow:** Define at which sample flow an alarm should be issued.

5.3.1.2.1 *Flow Alarm:* Program if the alarm relay should be activated if there is a flow alarm. Choose between yes or no. The flow alarm will always be indicated in the display, pending error list, saved in the message list and the logger.

Available values: Yes or no

NOTICE: *Sufficient flow is essential for a correct measurement. We recommend to program yes.*

5.3.1.2.2 *Alarm High:* If the measuring values rises above the programmed value E009 will be issued.

Range: 9–20 l/h

5.3.1.2.35 *Alarm Low:* If the measuring values falls below the programmed value E010 will be issued.

Range: 5–8 l/h

5.3.1.3 Sample Temp.

5.3.1.3.1 *Alarm High:* If the measured value rises above the alarm high value, the alarm relay is activated and E007, is displayed in the message list.

Range: 30–200 °C

5.3.1.3.25 *Alarm Low:* If the measured value falls below the alarm low value, the alarm relay is activated and E008 is displayed in the message list.

Range: -10 to +20 °C

5.3.1.4 Case Temp.

5.3.1.4.1 *Case Temp. high:* Set the alarm high value for temperature of electronics housing. If the value rises above the programmed value E013 is issued.

Range: 30–75 °C

5.3.1.4.2 *Case Temp. low:* Set the alarm low value for temperature of electronics housing. If the value falls below the programmed value E014 is issued.

Range: -10 to +20 °C

5.3.1.5 **Alarm Concentration:** Visible if a Conc. parameter has been selected. TDS is displayed in mg/l, all other parameters are displayed in %.

5.3.1.5.1 *Alarm High:* If the measured value rises above the alarm high value, the alarm relay is activated and E003, is displayed in the message list.

Range: 0.00%–99.90%

5.3.1.5.25 *Alarm Low:* If the measured value falls below the alarm low value, the alarm relay is activated and E004 is displayed in the message list.

Range: 0.00%–99.90%

5.3.1.5.35 *Hysteresis:* Within the hyst. range, the relay does not switch. This prevents damage of relays contacts when the measured value fluctuates around the alarm value.

Range: 0.00%–99.90%

5.3.1.5.45 *Delay:* Duration, the activation of the alarm relay is retarded after the measuring value has risen above or fallen below the programmed alarm.

Range: 0–28'800 Sec

5.3.2 and 5.3.3 Relay 1 and 2: The function of relay contacts 1 or 2 are defined by the user.

NOTICE: The navigation in the menu <Relay 1> and <Relay 2> is identical. For reason of simplicity only the menu numbers of Relay 1 are used in the following.

- 1 First select the functions as:
 - Limit upper/lower,
 - Control upwards/downwards,
 - Timer
 - Fieldbus
- 2 Then enter the necessary data depending on the selected function.

5.3.2.1 Function = Limit upper/lower:

When the relays are used as upper or lower limit switches, program the following:

- 5.3.2.20 *Parameter:* select a process value
- 5.3.2.300 *Setpoint:* If the measured value rises above respectively falls below the set-point, the relay is activated.

Parameter	Range
Conductivity	0 μ S–300 mS
Temperature	-25 to +270 °C
Sample flow	0–50 l/h
Cond. uc	0 μ S–300 mS

- 5.3.2.400 *Hysteresis:* within the hysteresis range, the relay does not switch. This prevents damage of relay contacts when the measured value fluctuates around the alarm value.

Parameter	Range
Conductivity	0 μ S–300 mS
Temperature	-25 to +270 °C
Sample flow	0–50 l/h
Cond. uc	0 μ S–300 mS

- 5.3.2.50 *Delay:* Duration, the activation of the alarm relay is retarded after the measuring value has risen above/fallen below the programmed alarm.
Range. 0–600 Sec

5.3.2.1 Function = Control upwards/downwards:

The relays may be used to drive control units such as solenoid valves, membrane dosing pumps or motor valves. When driving a motor valve both relays are needed, relay 1 to open and relay 2 to close the valve.

5.3.2.22 *Parameter*: Choose on of the following process values.

- ◆ Conductivity)
- ◆ Temperature
- ◆ Sample Flow
- ◆ Cond. uc

5.3.2.32 **Settings**: Choose the respective actuator:

- ◆ Time proportional
- ◆ Frequency
- ◆ Motor valve

5.3.2.32.1 Actuator = Time proportional

Examples of metering devices that are driven time proportional are solenoid valves, peristaltic pumps.

Dosing is controlled by the operating time.

5.3.2.32.20 *Cycle time*: duration of one control cycle (on/off change).

Range: 0–600 sec.

5.3.2.32.30 *Response time*: Minimal time the metering device needs to react.

Range: 0–240 sec.

5.3.2.32.4 **Control Parameters**

Range for each Parameter same as [5.2.1.43, p. 47](#)

5.3.2.32.1 Actuator = Frequency

Examples of metering devices that are pulse frequency driven are the classic membrane pumps with a potential free triggering input. Dosing is controlled by the repetition speed of dosing shots.

5.3.2.32.21 *Pulse frequency*: Max. pulses per minute the device is able to respond to. Range: 20–300/min.

5.3.2.32.31 **Control Parameters**

Range for each Parameter same as [5.2.1.43, p. 47](#)

5.3.2.32.1 Actuator = Motor valve

Dosing is controlled by the position of a motor driven mixing valve.

- 5.3.2.32.22 *Run time*: Time needed to open a completely closed valve
Range: 5–300 Sec.
- 5.3.2.32.32 *Neutral zone*: Minimal response time in % of the runtime. If the requested dosing output is smaller than the response time, no change will take place.
Range: 1–20 %

5.3.2.32.4 Control Parameters

Range for each Parameter same as [5.2.1.43, p. 47](#)

5.3.2.1 Function = Timer:

The relay will be activated repetitively depending on the programmed time scheme.

- 5.3.2.24 *Mode*: Operating mode (interval, daily, weekly)

5.3.2.24 Interval

- 5.3.2.340 *Interval*: The interval can be programmed within a range of 1–1'440 min.

- 5.3.2.44 *Run Time*: Enter the time the relay stays active.
Range: 5–32'400 sec.

- 5.3.2.54 *Delay*: during run time plus the delay time the signal and control outputs are held in the operating mode programmed below.
Range: 0–6'000 Sec.

- 5.3.2.6 *Signal Outputs*: Select operating mode of the signal output:

Cont.: Signal outputs continue to issue the measured value.

Hold: Signal outputs hold the last valid measured value.
Measurement is interrupted. Errors, except fatal errors, are not issued.

Off: Signal outputs are switched off (set to 0 or 4 mA).
Errors, except fatal errors, are not issued.

- 5.3.2.7 *Output/Control*: Select operating mode of the controller output:

Cont.: Controller continues normally.







Hold: Controller continues based on the last valid value.

Off: Controller is switched off.

5.3.2.24 *daily*

The relay contact can be activated daily, at any time of a day.

5.3.2.341 *Start time*: to set the start time proceed as follows:

- 1 Press [Enter], to set the hours.
- 2 Set the hour with the [] or [] keys.
- 3 Press [Enter], to set the minutes.
- 4 Set the minutes with the [] or [] keys.
- 5 Press [Enter], to set the seconds.
- 6 Set the seconds with the [] or [] keys.

Range: 00:00:00–23:59:59

5.3.2.44 *Run Time*: see Interval

5.3.2.54 *Delay*: see Interval

5.3.2.6 *Signal Outputs*: see Interval

5.3.2.7 *Output/Control*: see Interval

5.3.2.24 *weekly*

The relay contact can be activated at one or several days, of a week. The daily starting time is valid for all days.

5.3.2.342 **Calendar**:

5.3.2.342.1 *Start time*: The programmed start time is valid for each of the programmed days. To set the start time see [5.3.2.341, p. 54](#).

Range: 00:00:00–23:59:59

5.3.2.342.2 *Monday*: Possible settings, on or off to

5.3.2.342.8 *Sunday*: Possible settings, on or off

5.3.2.44 *Run Time*: see Interval

5.3.2.54 *Delay*: see Interval

5.3.2.6 *Signal Outputs*: see Interval

5.3.2.7 *Output/Control*: see Interval

5.3.2.1 **Function = Fieldbus**:

The relay will be switched via the Profibus input. No further parameters are needed.

- 5.3.4 Input:** The functions of the relays and signal outputs can be defined depending on the position of the input contact, i.e. no function, closed or open.
- 5.3.4.1 **Active:** Define when the input should be active:
- No:* Input is never active.
- When closed* Input is active if the input relay is closed
- When open:* Input is active if the input relay is open
- 5.3.4.2 **Signal Outputs:** Select the operation mode of the signal outputs when the relay is active:
- Cont.:* Signal outputs continue to issue the measured value.
- Hold:* Signal outputs issue the last valid measured value. Measurement is interrupted. Errors, except fatal errors, are not issued.
- Off:* Set to 0 or 4 mA respectively. Errors, except fatal errors, are not issued.
- 5.3.4.3 **Output/Control:** (relay or signal output):
- Cont.:* Controller continues normally.
- Hold:* Controller continues on the last valid value.
- Off:* Controller is switched off.
- 5.3.4.4 **Fault:**
- No:* No message is issued in pending error list and the alarm relay does not close when input is active. Message E024 is stored in the message list.
- Yes:* Message E024 is issued and stored in the message list. The Alarm relay closes when input is active.
- 5.3.4.5 **Delay:** Time which the instrument waits, after the input is deactivated, before returning to normal operation.
Range: 0–6'000 Sec

5.4 Miscellaneous

- 5.4.1 *Language*: Set the desired language.

Language
German
English
French
Spanish

- 5.4.2 *Set defaults*: Reset the instrument to factory default values in three different ways:

Set defaults
no
Calibration
In parts
Completely

- ♦ **Calibration**: Sets calibration values back to default. All other values are kept in memory.
- ♦ **In parts**: Communication parameters are kept in memory. All other values are set back to default values.
- ♦ **Completely**: Sets back all values including communication parameters.

- 5.4.3 *Load Firmware*: Firmware updates should be done by instructed service personnel only.

Load Firmware
no
yes

- 5.4.4 **Password**: Select a password different from 0000 to prevent unauthorized access to the following menus:

- 5.4.4.1 Messages
- 5.4.4.2 Maintenance
- 5.4.4.3 Operation
- 5.4.4.4 Installation.

Each menu may be protected by a *different* password.

If you forgot the passwords, contact the closest SWAN representative.

- 5.4.5 *Sample ID*: Identify the process value with any meaning full text, such as KKS number.

5.5 Interface

Select one of the following communication protocols. Depending on your selection, different parameters must be defined.

5.5.1 *Protocol: Profibus*

- 5.5.20 Device address: Range: 0–126
- 5.5.30 ID-Nr.: Range: Analyzer; Manufacturer; Multivariable
- 5.5.40 Local operation: Range: Enabled, Disabled

5.5.1 *Protocol: Modbus RTU*

- 5.5.21 Device address: Range: 0–126
- 5.5.31 Baud Rate: Range: 1200–115200 Baud
- 5.5.41 Parity: Range: none, even, odd

5.5.1 *Protocol: HyperTerminal*

- Baud Rate: Range: 1200–115200 Baud

10. Default Values

Operation:

Sensors:	Filter Time Const.:	10 s
	Hold after Cal.:	300 s
Relay Contacts	Alarm Relay	same as in Installation
	Relay 1/2	same as in Installation
	Input.....	same as in Installation
Logger:	Logger Interval:	30 min
	Clear Logger:	no

Installation:

Sensors	Sensor Parameters; Cell Constant	0.4000 cm ⁻¹
	Sensor Parameters; Temp. corr.	0.00 °C
	Sensor Parameters; Cable length.....	0.0 m
	Temp. Compensation; Comp.	none
	Flow; Flow measurement.....	none
	Conc.:	none
Signal Output 1	Parameter:	Conductivity
	Current loop:	4 – 20 mA
	Function:	linear
	Scaling: Range low:	0.000 µS
	Scaling: Range high:	100 mS
Signal Output 2	Parameter:	Temperature
	Current loop:	4 – 20 mA
	Function:	linear
	Scaling: Range low:	0.0 °C
	Scaling: Range high:	50.0 °C
Alarm Relay:	Alarm Conductivity:	
	Alarm high:	300 mS
	Alarm low:	0.00 µS
	Hysteresis:	1.00 mS
	Delay:	5 s
	Sample Flow (if Flow measurement = yes):	
	Flow Alarm	yes
	Alarm high:	50.0 l/h
	Alarm low:	5.0 l/h
	Sample Temp:	
	Alarm High:	120 °C
	Alarm Low:	0 °C

	Case Temp. high:.....	65 °C
	Case Temp. low:	0 °C
Relay 1 and 2	Function:.....	limit upper
	Parameter:.....	Conductivity
	Setpoint:	100 mS
	Hysteresis:	1 mS
	Delay:	30 s
	If Function = Control upw. or dnw:	
	Parameter:.....	Conductivity
	Settings: Actuator:	Frequency
	Settings: Pulse Frequency:	120/min
	Settings: Control Parameters: Setpoint:	100 mS
	Settings: Control Parameters: P-band:	1 mS
	Settings: Control Parameters: Reset time:	0 s
	Settings: Control Parameters: Derivative Time:	0 s
	Settings: Control Parameters: Control Timeout:	0 min
	Settings: Actuator:	Time proportional
	Cycle time:	60 s
	Response time:	10 s
	Settings: Actuator	Motor valve
	Run time:	60 s
	Neutral zone:	5%
	If Function = Timer:	
	Mode:.....	Interval
	Interval:	1 min
	Mode:	daily
	Start time:	00.00.00
	Mode:.....	weekly
	Calendar; Start time:	00.00.00
	Calendar; Monday to Sunday:	Off
	Run time:	10 s
	Delay:	5 s
	Signal output:	cont
	Output/Control:	cont
Input:	Active	when closed
	Signal Outputs	hold
	Output/Control	off
	Fault	no
	Delay	10 s

Miscellaneous	Language:..... English
	Set default:.....no
	Load firmware:.....no
	Password:..... for all modes 0000
	Sample ID:..... - - - - -
Interface	Protocol:..... Hyperterminal

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Notes

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